

# FURUNO

# OPERATOR'S MANUAL

COLOR SCANNING SONAR

MODEL CSH-23/24



**FURUNO ELECTRIC CO., LTD.**  
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# SAFETY INSTRUCTIONS

## **WARNING**



### **Do not open the equipment.**

Hazardous voltage which can cause electrical shock exists inside the equipment. Only qualified personnel should work inside the equipment.

### **Immediately turn off the power at the switchboard if water leaks into the equipment or something is dropped in the equipment.**

Continued use of the equipment can cause fire or electrical shock. Contact a FURUNO agent for service.

### **Do not disassemble or modify the equipment.**

Fire, electrical shock or serious injury can result.

### **Do not place liquid-filled containers on the top of the equipment.**

Fire or electrical shock can result if a liquid spills into the equipment.

### **Immediately turn off the power at the switchboard if the equipment is emitting smoke or fire.**

Continued use of the equipment can cause fire or electrical shock. Contact a FURUNO agent for service.

### **Make sure no rain or water splash leaks into the equipment.**

Fire or electrical shock can result if water leaks in the equipment.

## **WARNING**

### **Keep heater away from equipment.**

A heater can melt the equipment's power cord, which can cause fire or electrical shock.

### **Use the proper fuse.**

Fuse rating is shown on the equipment. Use of a wrong fuse can result in equipment damage.

### **Do not operate the equipment with wet hands.**

Electrical shock can result.



## **CAUTION**

**Do not exceed 18 knots when operating the equipment and do not exceed 16 knots when lowering or raising the transducer.**

The transducer may become damaged.

**The zinc block attached near the transducer must be replaced yearly.**

The junction between the transducer and main shaft may corrode, which can result in loss of the transducer or water leakage inside the ship.

**Do not use the equipment for other than its intended purpose.**

Use of the equipment as a stepping stool, for example, may result in personal injury or equipment damage.

**Replace the monitor when the picture becomes difficult to see.**

The average life of the monitor is about 10 years. Replace it when the picture becomes difficult to see, to protect vision.

**A warning label is attached to the equipment. Do not remove the label. If the label becomes soiled or illegible, contact a FURUNO agent or dealer.**

# TABLE OF CONTENTS

---

## FOREWORD

A Word to CSH-23/24 Owners .....	vii
Features .....	vii
System Configuration .....	viii

## CONTROL DESCRIPTION

Control Layout on Display Unit and Remote Control Box .....	1-1
Main Panel .....	1-2
Sub Panel 1 .....	1-4
Sub Panel 2 (data setting window) .....	1-5
Remote Control Box .....	1-8

## OPERATIONAL OVERVIEW

Turning the Power On/Off .....	2-1
Adjusting Screen Brilliance, Control Panel Backlighting .....	2-1
Lowering the Transducer .....	2-1
Selecting a Display Mode .....	2-2
Selecting a Display Range .....	2-3
Setting the Tilt Angle .....	2-3
Adjusting the Gain .....	2-7
Measuring Range and Bearing to a Target .....	2-7

## FINE TUNING THE PICTURE

Eliminating Unwanted Feeble Echoes .....	3-1
Suppressing Seabed Tail .....	3-3
Suppressing Seabed and Sea Surface Reflections in Shallow Waters .....	3-4
Rejecting Sonar Interference and Noise .....	3-4
Adjusting Beamwidth .....	3-6

## MARKS AND DATA

Marks, Data and Display Mode .....	4-1
Permanently Displayed Marks and Data .....	4-3
Erasable Marks and Data .....	4-4

## MENU OVERVIEW

USER Menu Operation .....	5-1
USER Menu Description .....	5-3
SYSTEM Menu Description .....	5-5
DATA SET Menu Description .....	5-8
INIT SET/TEST Menu Description .....	5-11

## **FUNCTION KEYS**

Programming the Function Keys .....	6-1
Replaying a Function Key .....	6-1
Saving Function Key Settings to a Memory Card .....	6-2
Replaying Function Key Settings from a Memory Card .....	6-2

## **ADVANCED LEVEL OPERATION**

Finding Fish School Center .....	7-1
Tracking a Fish School .....	7-2
Detecting Fish Schools Aurally .....	7-5
The Fish Alarm .....	7-6
Relocating Fish School for Easy Observation .....	7-7
Comparing Fish School Concentration .....	7-8
Measuring Fish School Speed .....	7-9
The Event Mark .....	7-10
True Motion Display .....	7-12
Plotting Net Location Mark .....	7-13
Observing Net Behavior .....	7-14
Target Slice Display .....	7-15

## **PORT/STARBOARD, HORIZONTAL SLICE DISPLAYS**

Port/Starboard Display .....	8-1
Horizontal Slice Display .....	8-2

## **MEMORY CARD OPERATIONS**

Initializing Memory Cards .....	9-1
Saving the Picture .....	9-2
Transferring Echo Data from Internal Memory to Memory Card .....	9-2
Saving Net Shooting Data .....	9-3
Replaying Saved Data .....	9-4
Deleting Memory Card Contents .....	9-4

## **TURNING MARKS, DATA ON/OFF .....**

10-1

## **INTERPRETING THE DISPLAY**

Seabed Echoes .....	11-1
Fish Schools .....	11-2
Sea Surface Reflections .....	11-3
Wake .....	11-3
False Echo by Sidelobe .....	11-4
Noise and Interference .....	11-4

**WARNINGS**

Overvoltage Warning ..... 12-1  
Unretracted Transducer Warning ..... 12-1

**SELF TESTS**

Opening the Self Test Menu ..... 13-1  
Self Test Description ..... 13-2  
Interface Unit CS-120A Self Test ..... 13-5

**INPUT DATA SELECTION**

Selection of Data at Interface Unit CS-120A ..... 14-1  
Setting Distances Between Net Sonde Transmitters ..... 14-2

**MAINTENANCE**

Display Unit Maintenance ..... 15-1  
Hull Unit Maintenance ..... 15-2

**MENU TREE** ..... A-1

**SPECIFICATIONS** ..... SP-1

**INDEX** ..... IN-1

# FOREWORD

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## A Word to CSH-23/24 Owners

Congratulations on your choice of the FURUNO CSH-23/24 Color Scanning Sonar. We are confident you will see why the FURUNO name has become synonymous with quality and reliability.

For over 40 years FURUNO Electric Company has enjoyed an enviable reputation for quality marine electronics equipment. This dedication to excellence is furthered by our extensive global network of agents and dealers.

This equipment is designed and constructed to meet the rigorous demands of the marine environment. However, no machine can perform its intended function unless operated and maintained properly. Please carefully read and follow the recommended procedures for operation and maintenance.

We would appreciate hearing from you, the end-user, about whether we are achieving our purposes.

Thank you for considering and purchasing FURUNO equipment.

## Features

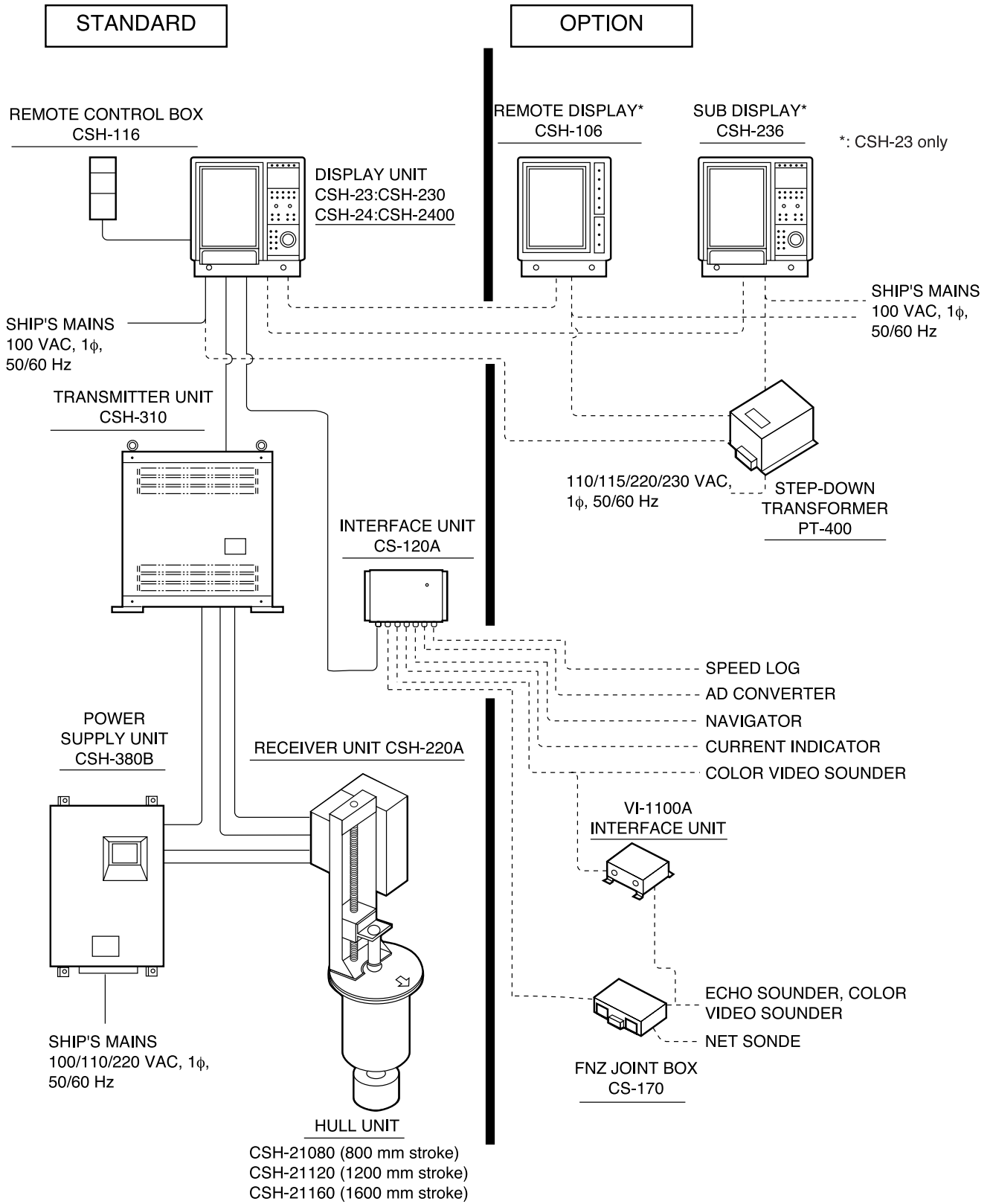
The FURUNO CSH-23/24 Color Scanning Sonar is a full-circle, multibeam electronic scanning sonar which detects and instantaneously displays fish schools and underwater conditions in 16 colors on a 15/21" non-glare, high resolution CRT screen.

The main features of the CSH-23/24 are

- Vivid 16-color display provides intuitive recognition of seabed and concentration, distribution and volume of fish schools.
- Markers and indications keep the operator abreast of fishing conditions.
- Remote control box provides for armchair control of major functions.
- New gain, range or tilt setting appears in large characters whenever corresponding control is adjusted.
- Function keys automatically setup the equipment to perform specific task.
- High power MOS FET transmitter ensures reliable operation under any condition.



# System Configuration



# CONTROL DESCRIPTION

## Control Layout on Display Unit and Remote Control Box

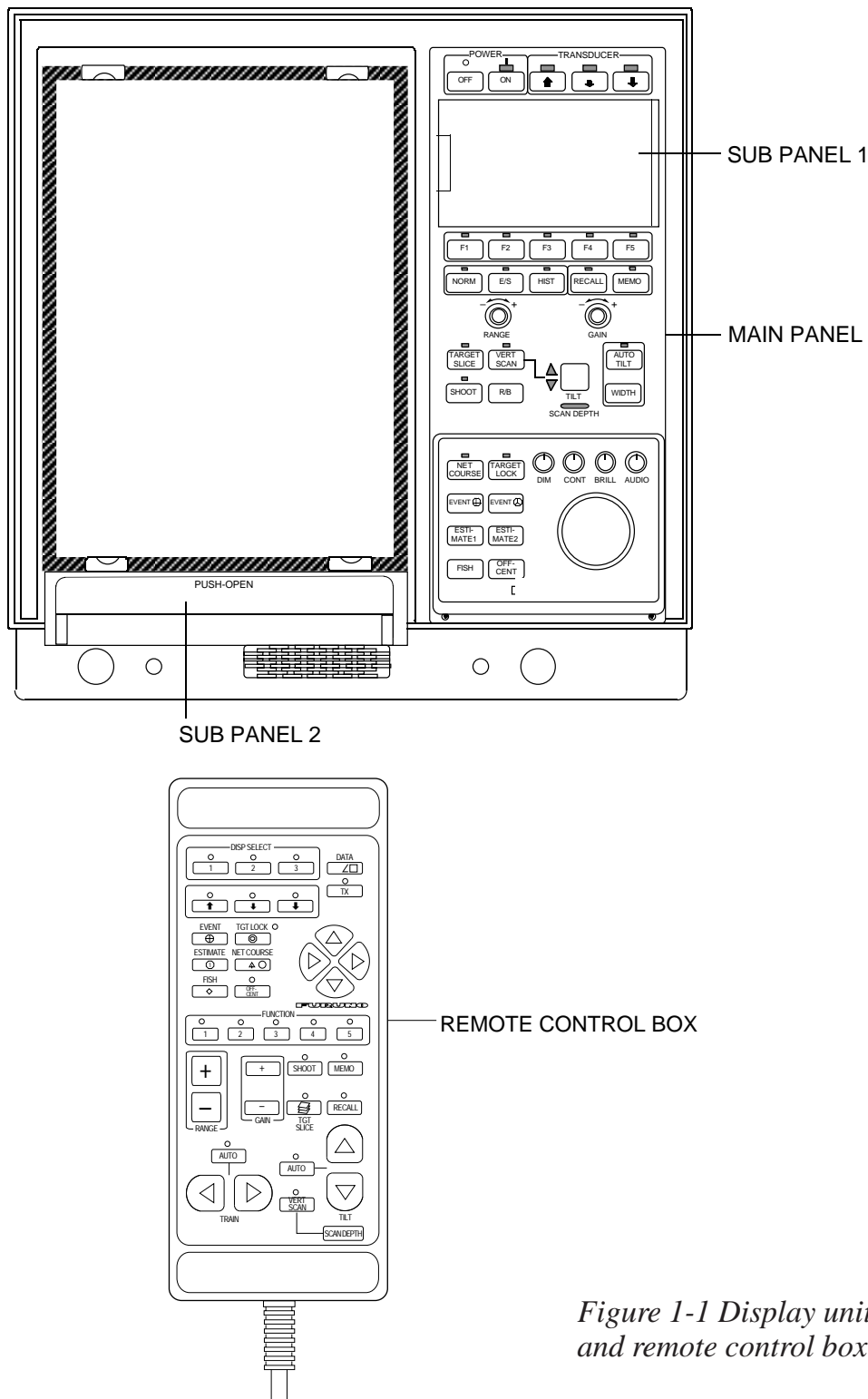


Figure 1-1 Display unit (CSH-23) and remote control box

# Main Panel

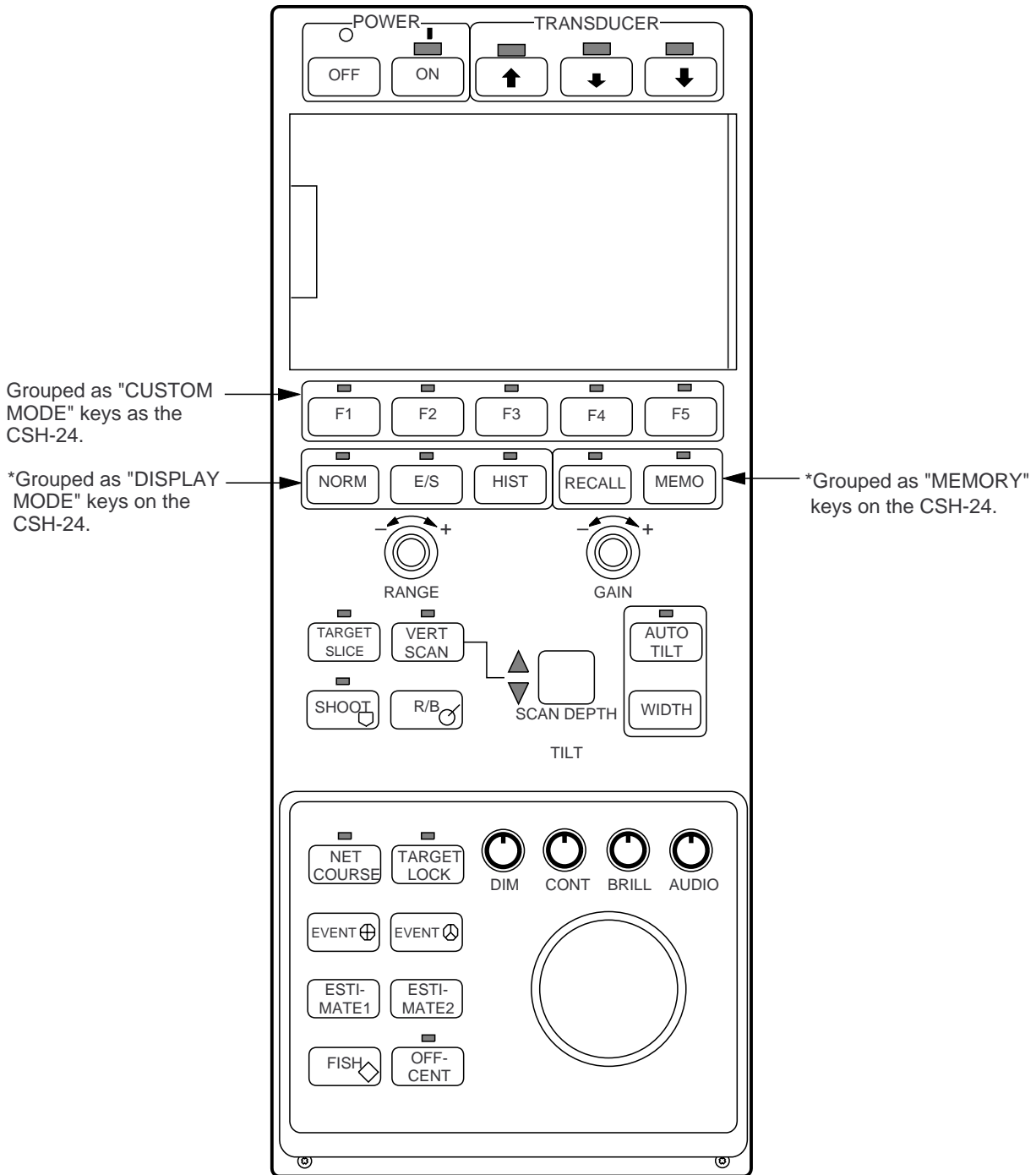


Figure 1-2 CSH-23 main panel

Main panel control description

Control	Function
POWER ON, POWER OFF	ON: Turns on the system. The lamp above the key lights during Tx and blinks when the TX key in sub panel 1 is turned off. OFF: Turns off the system. Press after retracting the transducer.
TRANSDUCER ↑ ↓ ↓	Raise and lower the transducer. ↓, ↓ are mid-protrusion and full protrusion, respectively. ↑ raises the transducer.
F1-F5	Setup panel controls and menu settings according to preset program.

Control	Function
NORM, E/S, HIST (Mode keys)	Select display mode: NORM, normal sonar picture; E/S, Echo sounder combination; HIST, Historical display. Lamp above a key lights to show current selection.
RECALL, MEMO	RECALL: Replays saved picture. MEMO: Saves picture to memory card or internal memory.
RANGE	Selects a picture display range. Range selected appears on the display.
GAIN	Adjusts receiver sensitivity.
TARGET SLICE	Using automatic tilting, displays the echo inside the estimate mark at several different tilt angles.
VERT SCAN	Not used.
SHOOT	Press when net is cast. The net shooting mark, *net sonde marks and *current mark appear at the own ship mark. The net shooting mark, net sonde marks and current mark move on the *ship's track as the ship moves. The lamp above the switch lights and time *distance run appears on the display until the net shooting mark is turned off.  (* Requires external sensor.)
R/B	Provides range and bearing data from own ship to a target. Select target with trackball and then press the R/B key. A line connects between own ship mark and trackball mark to show bearing to target.
TILT	Changes the tilt angle of the sounding beam between -5° and 60°.
AUTO TILT	Automatically tilts the sounding beam up and down in 2° steps within the tilt angle selected by the WIDTH key. The lamp above the key lights when automatic tilt is on.
WIDTH	Sets tilt width in automatic tilt.
NET COURSE	Marks location of net.
TARGET LOCK	Tracks a fish school.
EVENT ⊕ ⊗	Inscribe event mark on the display, to find horizontal, range, depth and bearing to a target. Event ⊗ key can be functioned as SHOOT key of remote control box.
ESTIMATE 1, 2	Compare volume of two fish schools.
FISH	Measures fish school speed.
OFF-CENT	Relocates selected target.
DIM	Adjusts the backlighting of the control panels and the brightness of the lamps above keys.
CONT	Adjusts screen contrast.
BRILL	Adjusts screen brilliance.
AUDIO	Adjusts volume of built-in loudspeaker, which monitors a target appearing along the bearing marker.
TRACKBALL	Follows on-screen movement of the trackball mark, to enter marks and off-center the screen.

# Sub Panel 1

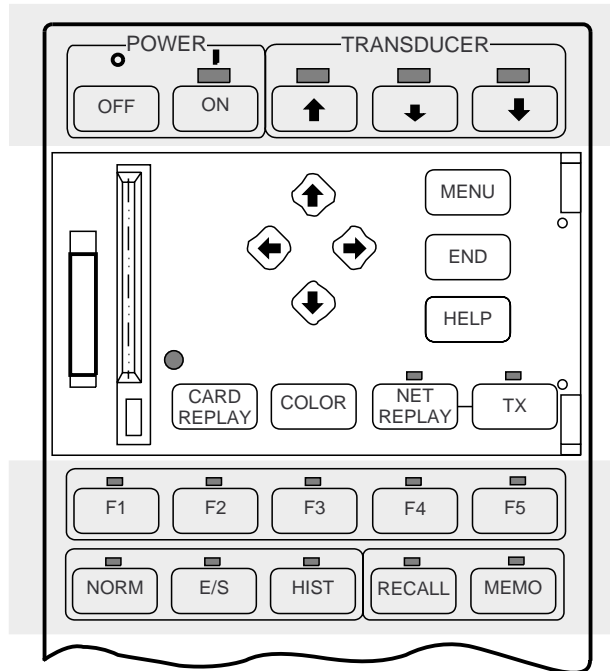
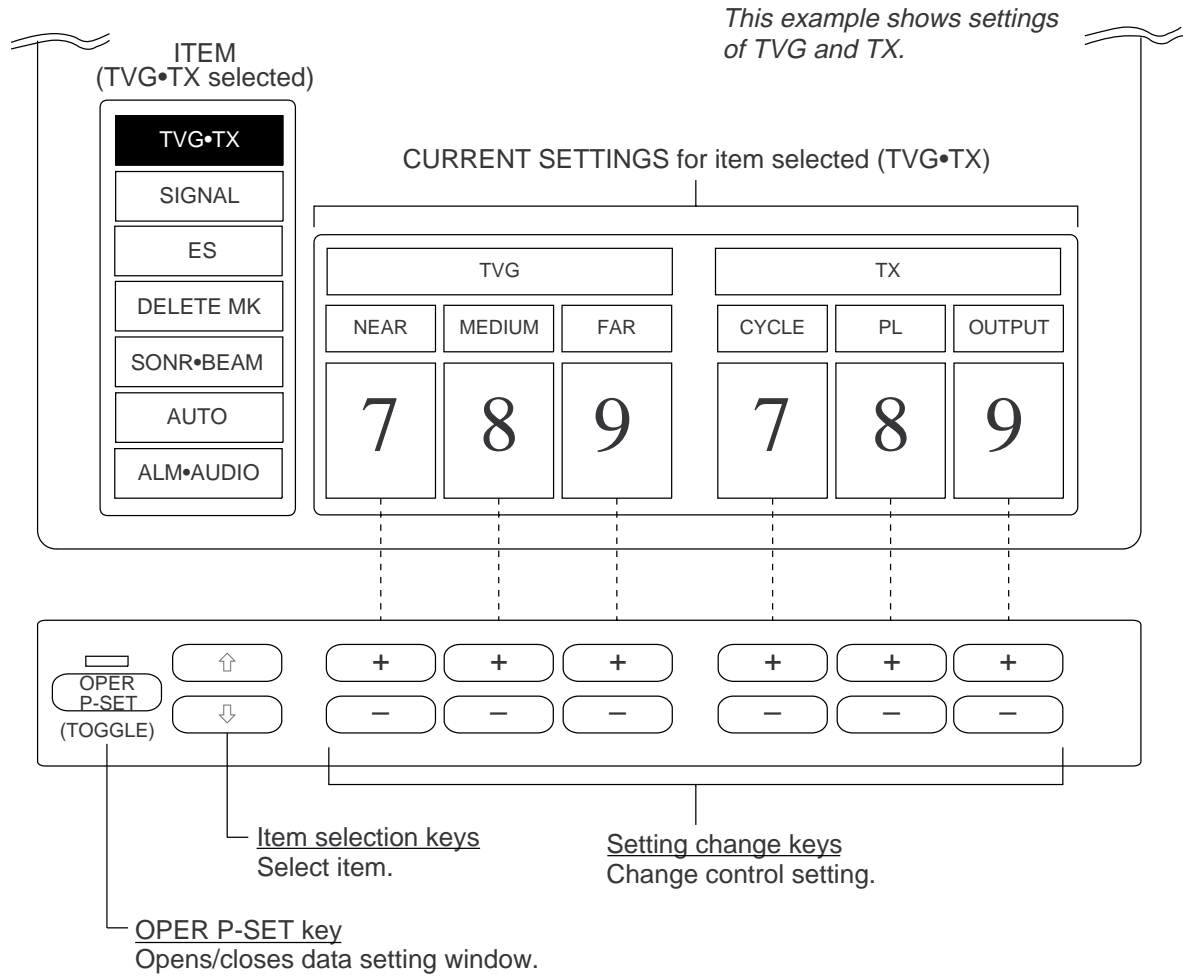


Figure 1-3 Sub panel 1

Sub panel 1 control description

Control	Function
MENU	Opens/closes the menu.
END	<ul style="list-style-type: none"> <li>• When the menu is displayed it terminates menu operation and returns control to the sonar picture.</li> <li>• When in a sub menu it returns control to previous sub menu.</li> </ul>
HELP	Provides operating information for current menu.
	Select items on menus.
CARD REPLAY	Replays card-stored control and menu settings.
COLOR	Changes display color among four choices.
NET REPLAY	Replays internally stored net shooting data. To replay, press key to light lamp above it, select item to replay, and press the key again.
TX	Press to transmit, when transducer is lowered. The lamp lights during transmission.

# Sub Panel 2 (data setting window)









*Figure 1-4 Sub panel 2*

## Sub panel 2 control description

Main Item	Item		Setting Range	Description	Normal Setting
	Main	Sub			
TVG•TX	TVG	NEAR	0-9	Adjusts receiver gain within 100 m.	5
		MEDIUM	0-9	Adjusts receiver gain between 100 m and 400 m.	5
		FAR	0-9	Adjusts receiver gain beyond 400 m.	5
	TRANSMIT	CYCLE	0-9	Sets Tx cycle. 9 is normal setting (fastest). "0" synchronizes with external KP.	9
		PL	0-9	Sets Tx pulselength. 9 is normal setting.	9
		OUTPUT	0-9	Sets Tx output power. 9 is maximum power.	9

*(Continued on next page)*

Main Item	Item		Setting Range	Description	Normal Setting	
	Main	Sub				
SIGNAL	SIGNAL PROCESS	NL	0-10	Rejects unwanted echoes.	3	
		AGC	0-10	Automatically reduces receiver gain against strong echoes such as seabed. Adjust so fish echo is displayed near seabed.	0	
		2AGC*	0-10	Suppresses seabed echoes. If AGC alone cannot suppress seabed echoes, use 2AGC.	0	
	SIGNAL PROCESS	CURVE	1-4	Selects echo level versus presentation color curve. The higher the setting, the easier it is to see weak echoes on the screen.	2	
		IR	0-3	Rejects random noise and interference by other echo sounders or sonars.	0	
		AFGLOW	0-4	Adjusts echo afterglow, which is useful for watching echo movement. The higher the setting the longer the afterglow remains.	0	
ES	ES1 (Net Recorder)	RANGE (DN RNG)	16 Pos.	Sets depth range of echo sounder picture. Sets range of net recorder downward sounding.	160 m	
		GAIN	0-10	Adjusts receive sensitivity.	5	
		SHIFT (UP RNG)	0-1000 m	Sets display start depth of echo sounder picture. Sets range of net recorder upward sounding.	0 m	
	ES1 (Net Recorder)	NL	0-10	Rejects blue dots (caused by dirty water) on entire screen.	0	
		COLOR	0-9	Eliminates echoes displayed in colors specified.	0	
		IR	ON, OFF	Eliminates interference by other sonars or echo sounders.	OFF	
DELETE MK	DELETE MARK		+ or - key to erase.	Each pressing erases oldest mark among event mark  , event mark  , fish mark, own ship mark.		
						
						
	DELETE MARK			TRACK	Each pressing deletes 1/5 of overall length.	
		FISH		FISH	Fish track is deleted.	

\*2AGC and HOR functions cannot be used together. If one is used the other is automatically set to "0".

(Continued on next page)

Main Item	Item		Setting Range	Description	Normal Setting
	Main	Sub			
SONR•BEAM	SONAR	SONAR	1–2	Choose "1" for single sonar, or "2" for dual sonar.	1
		F-SHIFT	1–2	Choose "2" to suppress interference by other sonars operating on same frequency, by shifting Tx frequency of CSH-23/24.	1
		UP/TM		Selects presentation mode among North-up (Nup), Heading up (Hup), True Motion (TM).	Hup
	BEAM	HOR*	0–10	Sets horizontal beamwidth of Rx beam. The higher the number, the narrower the beam.	0
		VER	0–4	Sets vertical beamwidth of transmission beam. "0" is normal setting. "1" and "2" for wide beam; "3" to reduce surface clutter; "4" to suppress false bottom echoes.	0
AUTO	AUTO TILT	ON/OFF	ON, OFF	Turns on/off scanning tilt angle	OFF
		WIDTH		WIDE:±2-10°, ±4-16°, ±6-20° NARROW:±1-4°, ±2-6°, ±3-8°	±2°-10°
	AUTO SCAN	ON/OFF	ON, OFF	Turns on/off scanning EBL, which scans audio sector.	OFF
		WIDTH		Chooses automatic scanning width among ±10°, ±20°, ±40° and ±60°.	±10∞
ALM•AUDIO	FISH ALARM	ON/OFF	ON, OFF	Turns fish alarm on/off.	OFF
		LEVEL	0–15	Sets echo level at which fish alarm sounds. Numbers 0–15 correspond to 16 presentation colors: 0, deep blue, 15, reddish brown.	10
		ZONE	Press +/- key.	Sets alarm zone, using the trackball and + key.	
	AUDIO	SECTOR		Chooses audio sector among 30°, 60°, 90°, 180° and 330°.	30°
		REVERB	0–9	Chooses length of reverberation for audio. Larger number gives longer reverberation.	0
		CENTER	Press +/- key.	Sets direction of audio sector, using the trackball and + key.	

*\*HOR and 2AGC functions cannot be used together. If one is used the other is automatically set to "0".*



# Remote Control Box

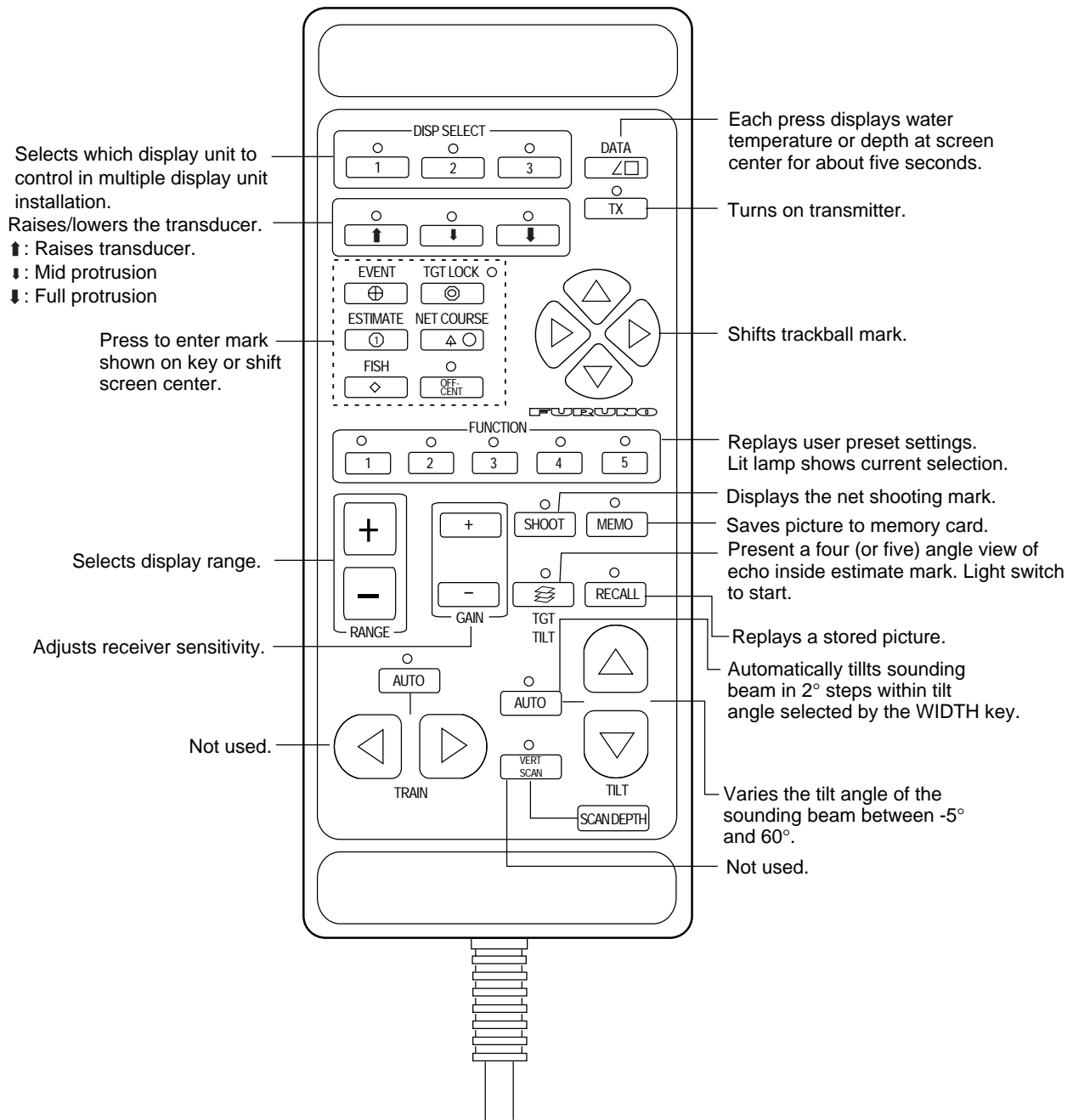


Figure 1-5 Remote control box

# OPERATIONAL OVERVIEW


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## Turning the Power On/Off

### Turning the power on

Press the ON switch on the main panel. The lamp above the switch should light. If it doesn't, press the TX switch on sub panel 1.

### Turning the power off




Retract the transducer with the  switch and then press the OFF switch on the main panel.

**Note:** The transducer is automatically retracted into the tank even if the OFF switch is pressed before retracting the transducer. However, make it a habit to retract the transducer before turning off the power.

## Adjusting Screen Brilliance, Control Panel Backlighting

The BRILL control adjusts screen brilliance, and the DIM control adjusts control panel backlighting. These controls are on the lower part of the main panel.

## Lowering the Transducer

Press  or  switch. The lamp above the switch blinks during lowering of the transducer and lights when the transducer is completely lowered. In normal use fully lower the transducer. The transducer extends \*1200 mm below the ship's hull, providing stable and cavitation-free soundings. If the transducer may become entangled in the net, after shooting the net, for example, partially raise the transducer with the  switch. This raises the transducer by 400 mm (transducer extends \*800 mm from ship's hull).

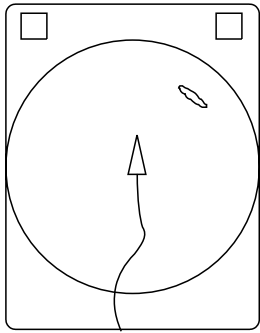
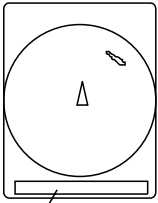
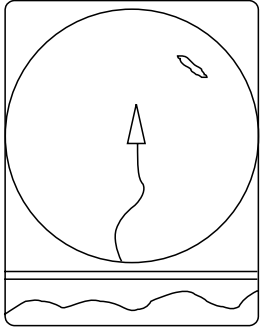
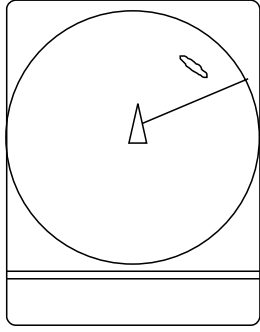
\*Hull unit with 1600mm (full) and 1200mm (mid) protrusions are also available.

 <b>CAUTION</b>
<b>Do not exceed speed noted in the specifications when operating the equipment or lowering or raising the transducer.</b>
The transducer may become damaged.
<b>Do not press the  switch during lowering of the transducer, and do not press the  or  switch during raising of the transducer.</b>
The equipment may become damaged.

# Selecting a Display Mode

The CSH-23/24 provides three display modes: normal sonar picture, echo sounder (E/S) combination, and history display combination. Those modes may be selected with the NORM, E/S and HIST keys.

*Table 2-1 Display mode description*

Mode	Description
 <p data-bbox="432 920 571 949">NORMAL</p>	<p data-bbox="676 562 1331 663">The sonar picture appears over the entire screen. This mode is useful for detecting and tracking fish schools.</p> <p data-bbox="676 667 1155 972">The default display area is 1.3 times the range, but it can be changed to 1.6 times the range on "EXT KP/TM DSP" in the SYSTEM menu. Navigation information can be displayed in the text window at the screen bottom by turning on "DATA DISPLAY" in the USER menu.</p>  <p data-bbox="1179 913 1337 943">Text window</p>
 <p data-bbox="483 1352 533 1382">E/S</p>	<p data-bbox="676 996 1331 1133">Normal scanning picture appears on the upper 5/8 of the screen and the signal fed from the echo sounder on the lower 3/8. This mode is suitable for judging fish school concentration.</p> <p data-bbox="676 1137 1283 1238">When two echo sounders are connected, each pressing of the E/S key alternately selects echo sounder 1 or echo sounder 2.</p> <p data-bbox="676 1243 1315 1341">Note that a net recorder can be connected as echo sounder 2; select it on the "ES" sub menu in the INIT SET/TEST menu.</p>
 <p data-bbox="432 1792 571 1821">HISTORY</p>	<p data-bbox="676 1435 1347 1641">Normal scanning sonar picture appears on the upper 5/8 of the screen and the history display on the lower 3/8. Three types of history displays are available: Audio, Port/Starboard and Horizontal Slice. You can select which one to display on the USER menu.</p>

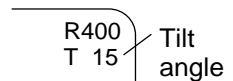
## Selecting a Display Range

Operate the RANGE control to select a display range. The selected range appears at the top of the screen.

## Setting the Tilt Angle

The tilt angle shows the direction to which the sound wave is emitted. When the sound wave is emitted horizontally, the tilt angle is said to be zero degrees and when emitted most downward, 60 degrees.

To set a tilt angle, operate the TILT lever. Watch the tilt angle indication at the top right corner on the screen. The tilt angle can be set in one-degree steps from -5 (upward) to 60° (downward) degrees.



Finding a proper tilt angle is important when searching for fish.

### Seabed echo and tilt angle

#### Case 1: Tilt angle 30 to 40 degrees

This tilt angle will display the entire seabed since it is captured by the full width of the beam.

#### Case 2: Tilt angle 10 to 20 degrees

This tilt angle will only display half the seabed since it is only captured by the lower half of the beam.

#### Case 3: Tilt angle 0 to 10 degrees

This tilt angle may or may not capture the seabed since the returning echo is weak.

## How to discriminate fish echoes from the seabed

The figure below illustrates how two fish schools (a) and (b) are displayed on the screen using three different tilt angles.

Case 1: Tilt angle 30 to 40 degrees. Fish school is obscured by the seabed.

Case 2: Tilt angle 10 to 20 degrees. Fish school is located above the seabed (midwater).

Case 3: Tilt angle 0 to 10 degrees. Fish school is located close to the seabed.

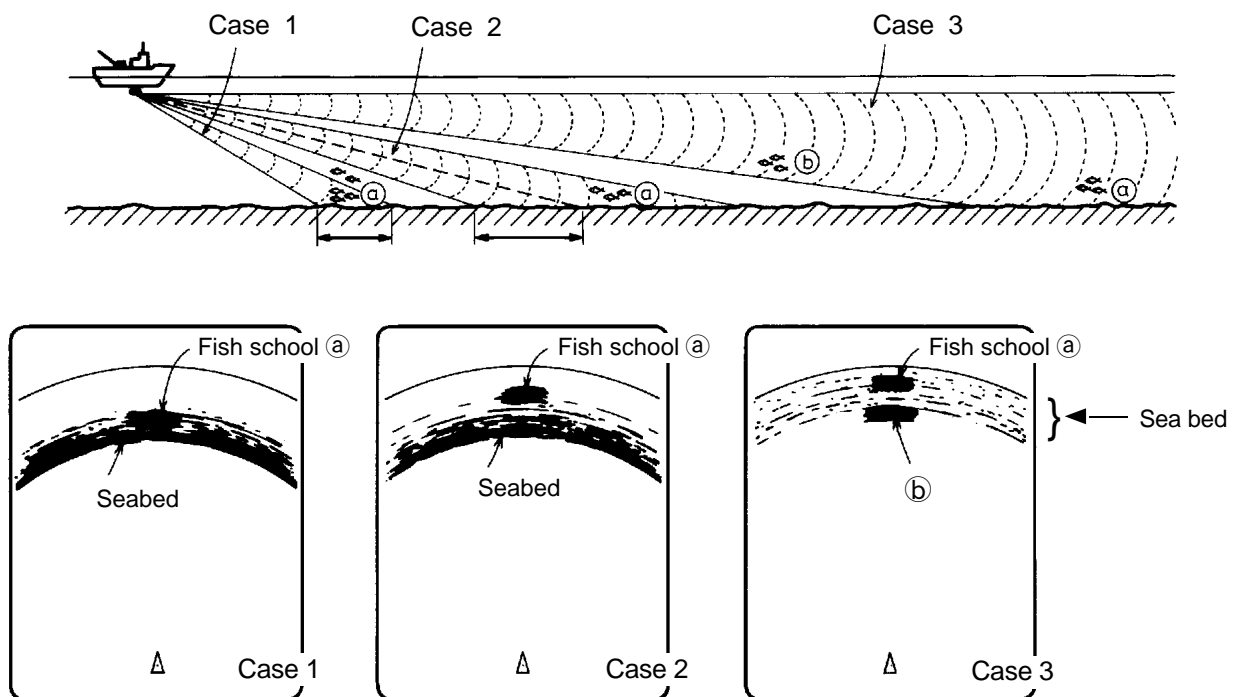


Figure 2-1 Fish echo and tilt angle

### Points to consider

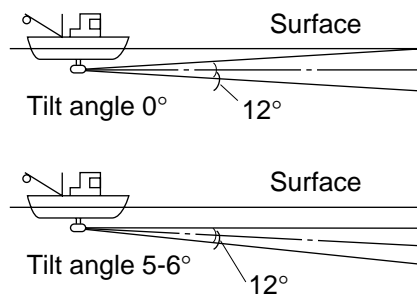
- Normally, a vertically distributed fish school is a better sonar target than the seabed, because it reflects the transmitted pulse back toward the transducer.
- In case 3, both fish schools (a) and (b) are presented. Generally speaking, however, midwater fish schools tend to be larger than bottom fish schools and they are often displayed near the seabed on the display.
- It is difficult to detect bottom fish when they are not distributed vertically.

## Tilt angle for surface fish

Sound emitted from the sonar transducer forms a circle-shaped beam with a width of approximately 12 degrees in the vertical direction (vertical beam width). The tilt angle is indicated by the angle between the center line of the beam and the horizontal plane. Then, if the tilt angle is set to 0 degrees, the center line is parallel with the sea surface and one half of the emitted sound goes upward, toward the sea surface.

This causes one half of the emitted sound to be reflected toward the transducer and displayed on the screen as sea surface reflections. When the sea is calm, since the sound is reflected just like a light hitting a mirror at a narrow incident angle, it propagates away and the sea surface reflections become negligible.

However if the sea is not calm enough, they will become dominant and interfere with observation of wanted echoes. To minimize these sea surface reflections and to search surface fish schools effectively, the tilt angle is usually set between 5 and 6 degrees so the upper portion of the beam becomes almost parallel with the sea surface. When the sea is rough, it is often set to a little larger angle.



*Figure 2-2 Tilt angle and sea surface reflections*

## Suitable tilt angle

The figure below illustrates the relationship among tilt angle, depth and detection range. Refer to it to find out the suitable tilt angle for a given depth/detection range.

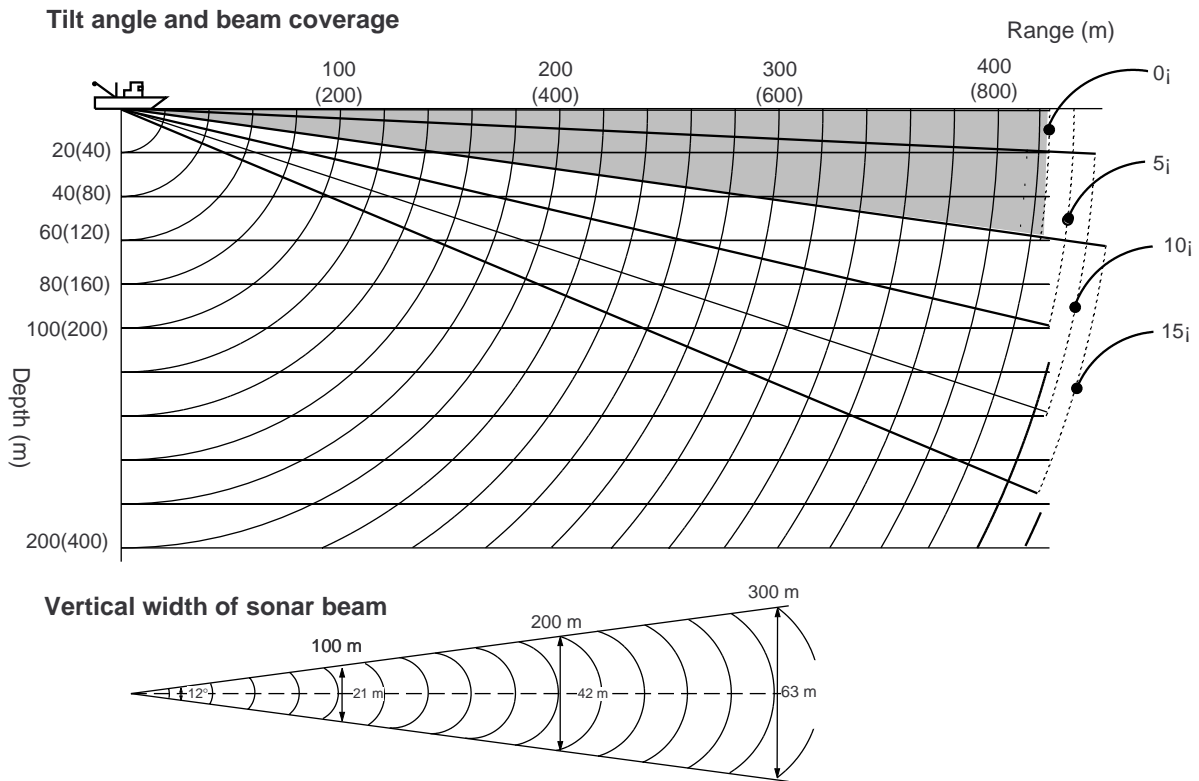


Figure 2-3 Tilt angle and beam coverage

## Adjusting the Gain

The GAIN control adjusts receiver sensitivity (gain). Adjust it so fish echoes are clearly displayed with minimal noise on the screen. Too high a setting not only displays excess noise and makes it difficult to discriminate wanted echoes but also causes seabed echoes to be painted in strong colors, resulting in echoes being masked by seabed reflections. Normally, set the control somewhere between positions “3” and “5”.

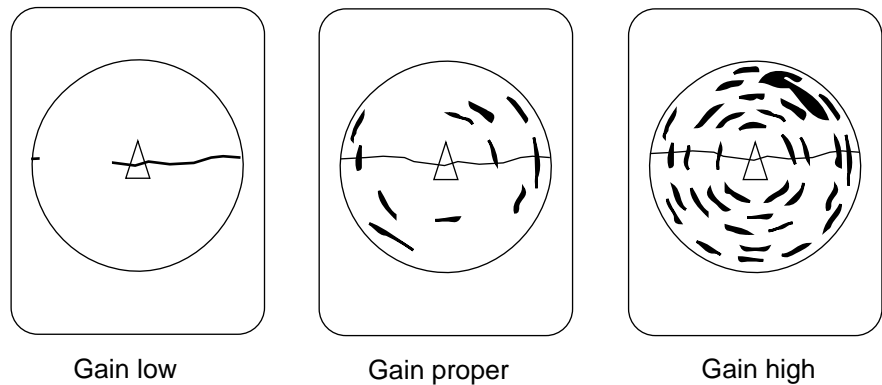


Figure 2-4 Gain settings and resulting picture

## Measuring Range and Bearing to a Target

Operate the trackball to place the trackball mark on the target you want to measure the range and bearing. The range and bearing appear at the upper left corner on the screen.

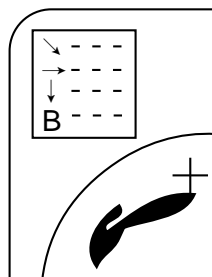


Figure 2-5 Location of range and bearing indications

Note: The bearing is shown in either 360° or 180° indication relative to ship’s heading. In the latter case, bearing (“B”) is indicated as follows:

B    P ----- on the port side  
 B    S ----- on the starboard side

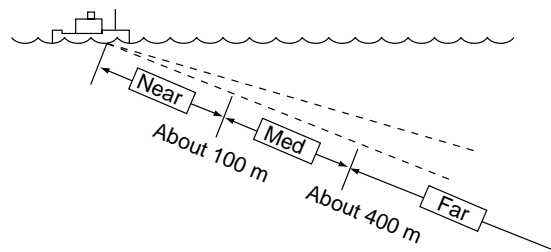


# FINE TUNING THE PICTURE

## Eliminating Unwanted Feeble Echoes

Echoes from targets such as seabed and fish return to the transducer in order of distance to them, and when we compare their intensities at the transducer face, those from nearer targets are generally stronger when their reflecting properties are nearly equal. The sonar operator will be quite inconvenienced if these echoes are directly displayed on the screen, since he can not judge the actual size of the target from the size of echoes displayed on the screen. To overcome this inconvenience, the TVG function is incorporated. It compensates for propagation loss of sound in water; amplification of echoes on short range is suppressed and gradually increased as range increases so that similar targets are displayed in the similar intensities irrespective of the ranges to them.

The CSH-23/24 has three TVG functions, NEAR, MEDIUM and FAR, and they mainly compensate for propagation loss on short, middle and long ranges respectively, centered at the ranges shown below. The higher the TVG setting the greater the amplification of echoes.



*Figure 3-1 Principle of TVG*

The TVG is also used to suppress unwanted echoes and noise which appear in a certain range area on the screen such as sea surface reflections and cruising noise. To set TVG properly, do the following:

### How to adjust TVG

1. Open sub panel 2.
2. Select TVG•TX.
3. Set TVG NEAR, MEDIUM and FAR to 5.  
(These are the standard settings and you can maintain them in most cases.)

4. When sea surface reflections or plankton layers disturb the picture, decrease appropriate TVG option by one or two steps by pressing – (minus) key.
5. When fish school is located on a long range setting (about 800 meters) which is approaching own ship.

Adjust the tilt to keep the fish school in the center of the sonar beam, namely, fish school is displayed in strongest colors possible. Confirm that the fish echo is displayed in the same color as it approaches. If the color suddenly changes to weaker colors as the fish enters MEDIUM and NEAR areas, the TVG is improperly set. Adjust the TVG. If this again produces sea surface reflections and noise try to remove them with AGC and NL controls.

**Note:** If the above procedure does not produce satisfactory results, the TVG curve can be changed on the SYSTEM menu. The 30 log setting is normal. The 25 log setting is useful for searching fish schools near shorelines or shallow waters. The 35 log or 40 log setting raises the gain on a long range and is suitable for searching tuna, bonito, etc., which are usually searched with high gain setting.

# Suppressing Seabed Tail

## **AGC (data setting window: SIGNAL, SIGNAL PROCESS)**

The AGC functions to automatically reduce the receiver gain only against strong echoes such as the seabed or a large fish school. Since weak echoes remain unaffected, a small fish school becomes easier to detect. Adjust it so that the AGC works only on seabed reflections. Do not set it too high; weak echoes may be missed.

## **Pulselength (data setting window: TVG•TX,PL)**

The pulselength control determines the length of the transmission pulse emitted into the water. While a longer pulse is advantageous for long range sounding, it has the disadvantage of being poor in discrimination of targets, that is, ability to separate several closely located targets. When searching bottom fish, therefore, it is useful to shorten the pulselength in order to separate fish echoes from seabed reflections. Decrease the PULSELENGTH setting to shorten the pulselength. For search of surface and midwater fish in which seabed reflections are not so strong, use the longest pulselength "9".

## **2AGC (data setting window: SIGNAL, SIGNAL PROCESS)**

While it is ideal to suppress seabed echoes with the AGC control alone there are some fishing grounds where this is not possible. (The high power sonar has the advantage of long-range detection but this can also be a disadvantage, since weaker echoes may be hidden in strong, unwanted echoes such as the seabed.)

If you cannot suppress seabed echoes or sea surface reflections by the AGC control alone, use the 2AGC control. Normally a setting of 2 or 3 is suitable. For especially strong echoes, use a setting of 4 or 5.

- 0: 2AGC function is off.
- 1 to 10: Larger the number, the greater the effect of 2AGC.

# Suppressing Seabed and Sea Surface Reflections in Shallow Waters

## Data setting window: TVG•TX, OUTPUT

In shallow fishing grounds with hard or rocky bottom, seabed reflections often interfere with wanted fish echoes and they can not be eliminated sufficiently with the aforementioned TVG and AGC controls, especially when the TILT is set to a larger angle in order to track fish schools approaching within 400 m. In such cases try to reduce the output power by adjusting the OUTPUT control instead of turning down the gain. The picture becomes clearer when output power is reduced rather than when the GAIN is decreased as illustrated below.

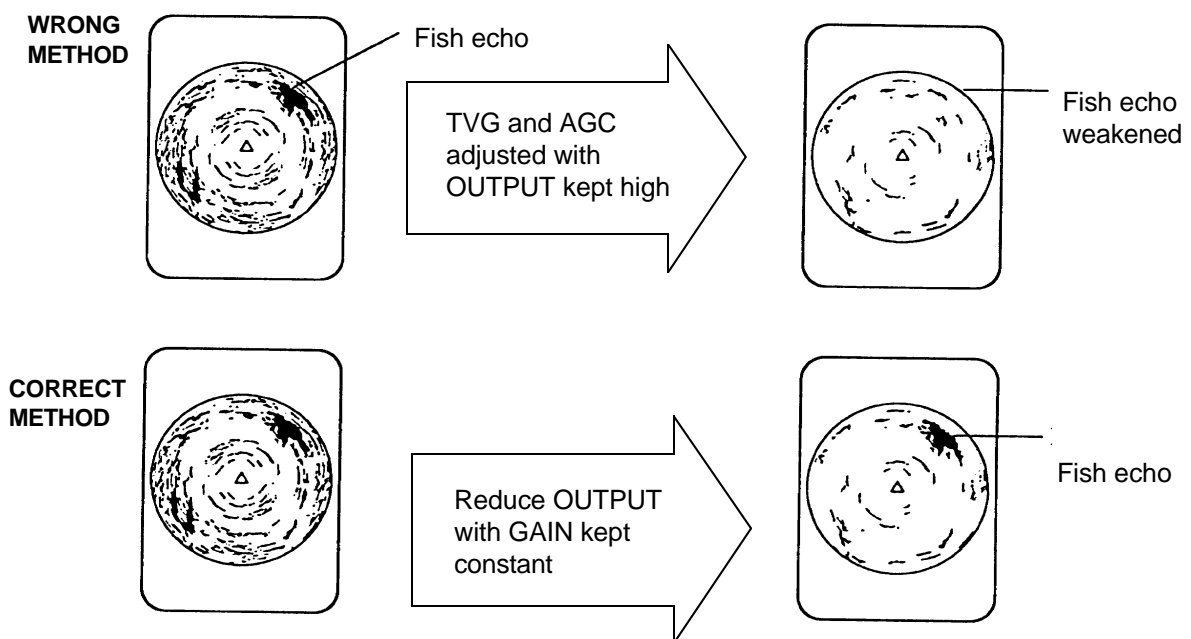


Figure 3-2 How to suppress seabed and sea surface reflections in shallow waters

## Rejecting Sonar Interference and Noise

While observing the sonar picture, you may encounter occasional or intermittent noise and interference. These are mostly caused by on-board electronic equipment, engine or propeller noise, or electrical noise from other sonars being operated nearby.

### Identifying noise source

To eliminate noise effectively, you should first identify the noise source as follows:

1. Turn off the TX switch and operate all on-board equipment one by one while observing the picture.
2. Run the boat at various speeds to check if the noise is speed dependent.

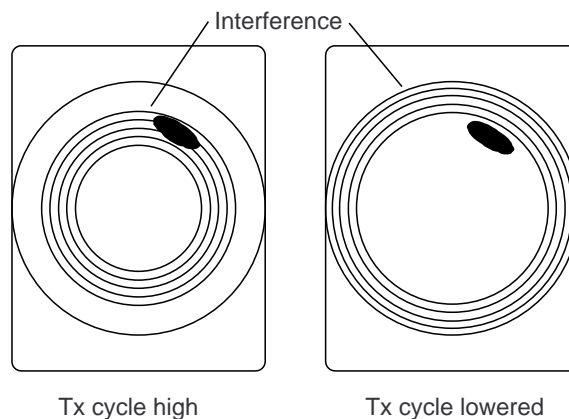
If neither of the above two steps has effect on the picture, adjust one of the following:

### **Interference rejector (data setting window: SIGNAL, SIGNAL PROCESS)**

This control is similar to the interference rejector on echo sounders and radars. It is effective for rejecting random noise and sea surface reflections in rough sea conditions. Set it so that noise is just eliminated. Do not use an unnecessarily high setting since it may also reject small wanted echoes.

### **Changing Tx cycle (data setting window: TVG•TX, CYCLE)**

When other sonars operate nearby at the same transmission interval as that of own ship's sonar, an interference ring caused by other sonars is displayed. To erase the interference ring from the screen, reduce the CYCLE on the data setting window.



*Figure 3-3 How CYCLE works*

**Note:** When the sonar is used in shallow water with the range set between 60 m and 200 m and Tx cycle at “9”, seabed reflections caused by the 2nd-to-the-last transmission may appear on near ranges. Reduce the Tx cycle setting to “2” or “3” to suppress them.

### Setting F-shift (data setting window: SONR•BEAM, SONAR)

If interference cannot be suppressed by the interference rejector (IR) or Tx cycle, change the setting of F-SHFT from 1 to 2.

### Noise limiter (data setting window: SIGNAL, SIGNAL PROCESS)

Weak, unwanted reflections, colored light-blue or green, appear when the water is dirty, plankton layers exists, or due to ship's noise. The noise limiter (NL) can reduce the effects of these unwanted reflections—raising the setting causes them to become bluish to background color. Normally a setting of 3 or 4 is sufficient.

## Adjusting Beamwidth

Beamwidth can be adjusted at SONR•BEAM, BEAM on the data setting window.

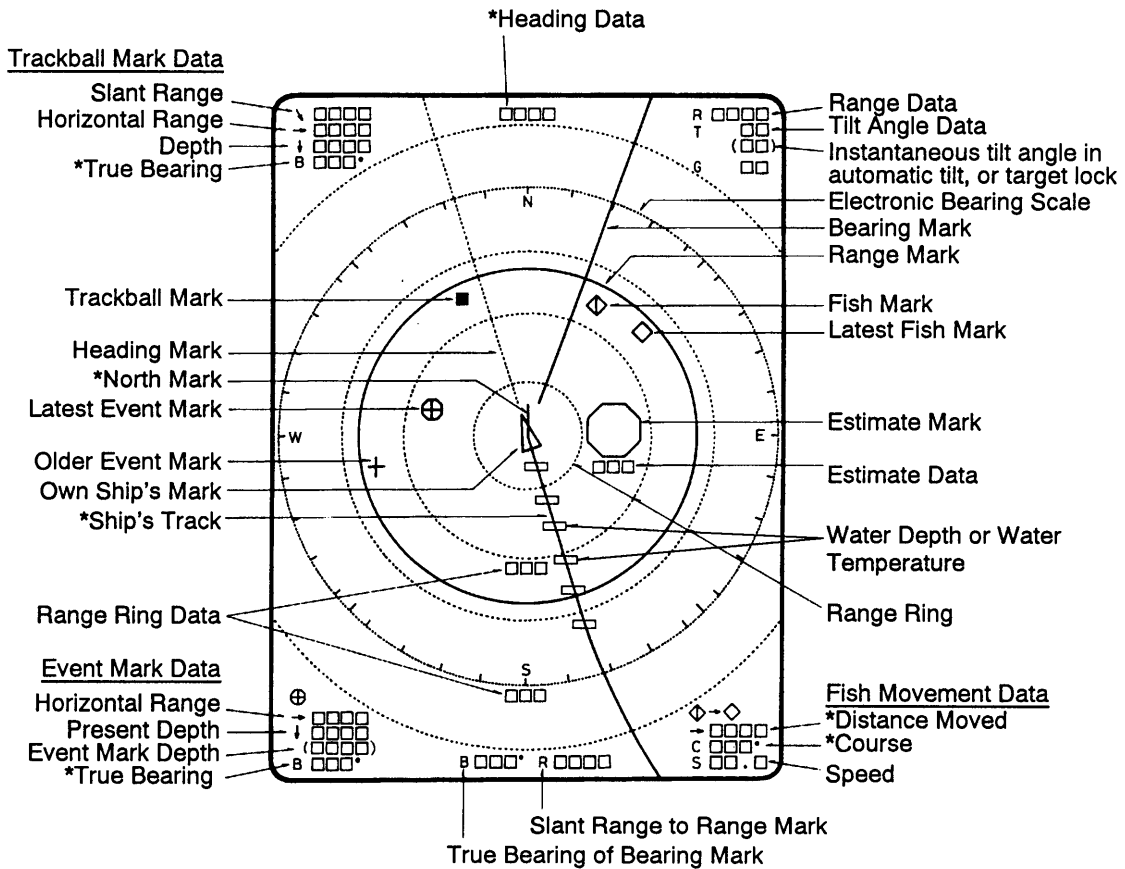
*Table 3-1 Beamwidth adjustment menus*

Menu	Application
HOR	Set to "0" for normal use. The higher the setting the narrower the beam. This control may be used together with the AGC and NL controls to suppress sea surface reflections and seabed echoes.
VER	<p>0: This is the normal beam. The higher the setting the narrower the beam. Increase the setting when searching for small fish schools or checking seabed condition.</p> <p>1 or 2: Provides a wide beam. It is useful for tracking quick moving fish schools such as bonito or tuna.</p> <p>3: This setting suppresses upper sidelobes (sea surface reflections) of the beam to make it easier to search fish schools.</p> <p>4: This setting suppresses lower sidelobes (seabed echo) of the beam to make it easier to search for fish near the seabed.</p>

# MARKS AND DATA

## Marks, Data and Display Mode

### Normal display mode



\*Requires external sensor.

Figure 4-1 Marks and data appearing in the normal display mode

## Normal display mode w/text

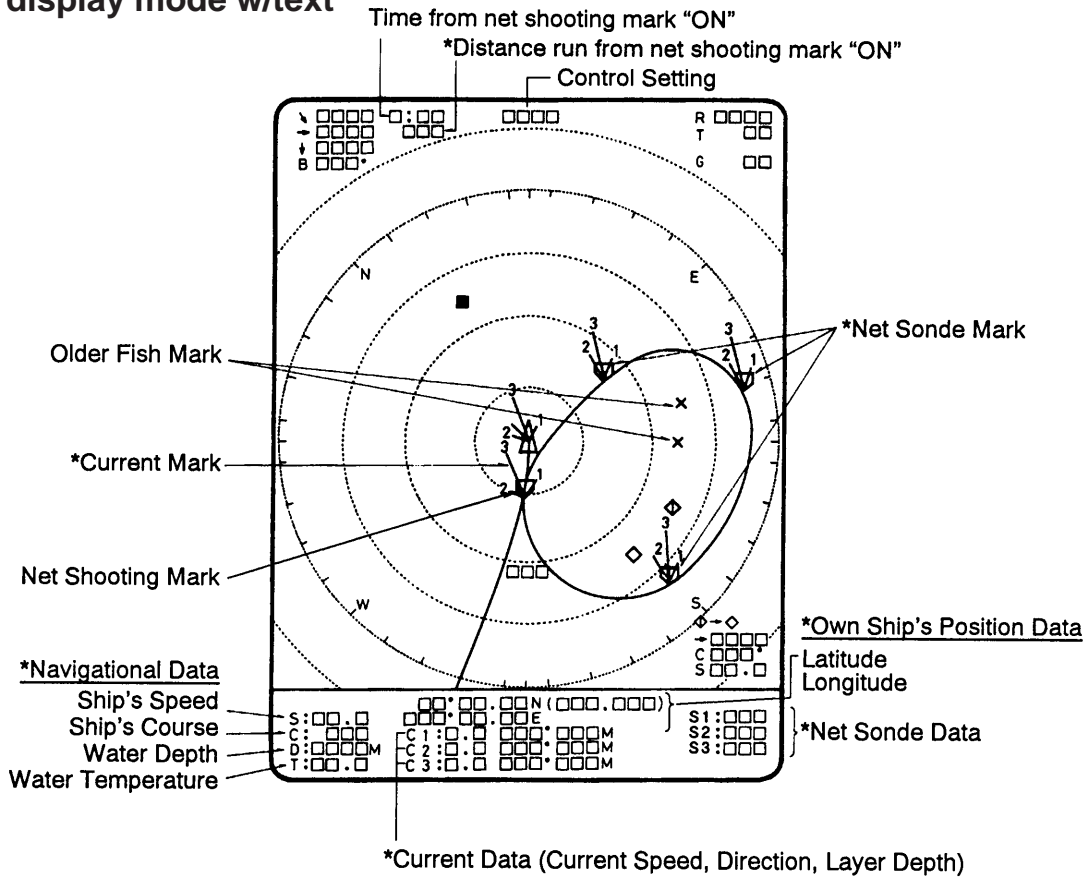


Figure 4-2 Marks and data appearing in the normal display mode w/text

## Echo sounder combination display

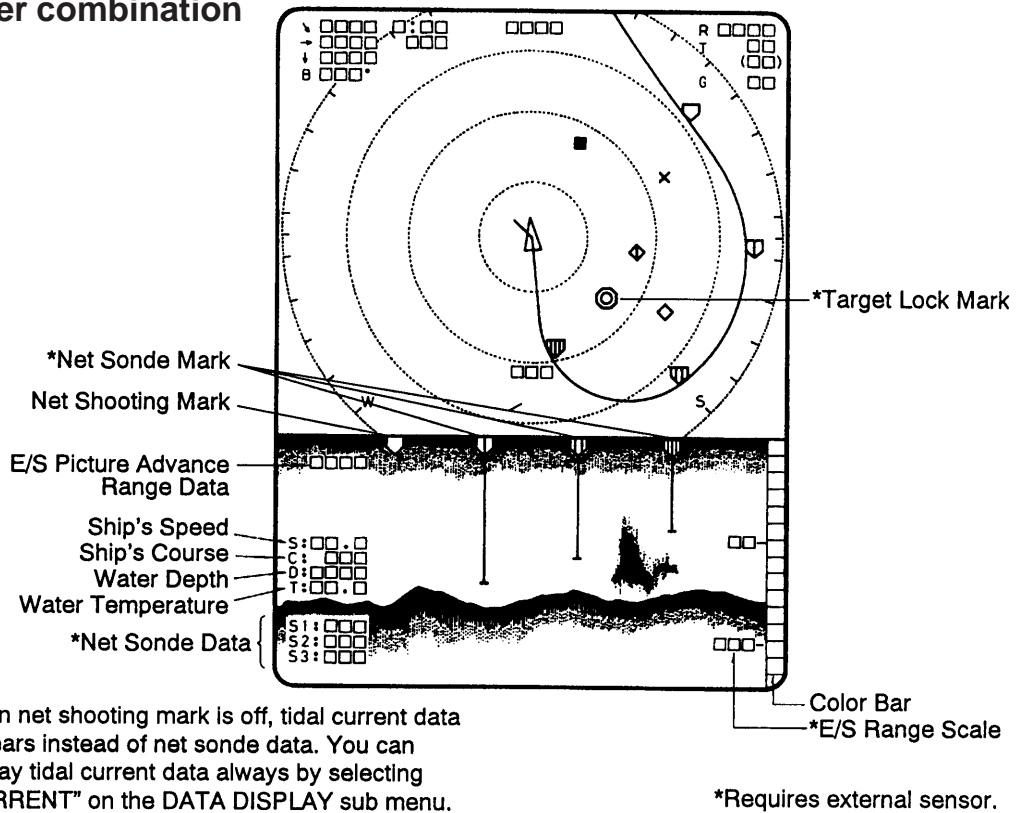
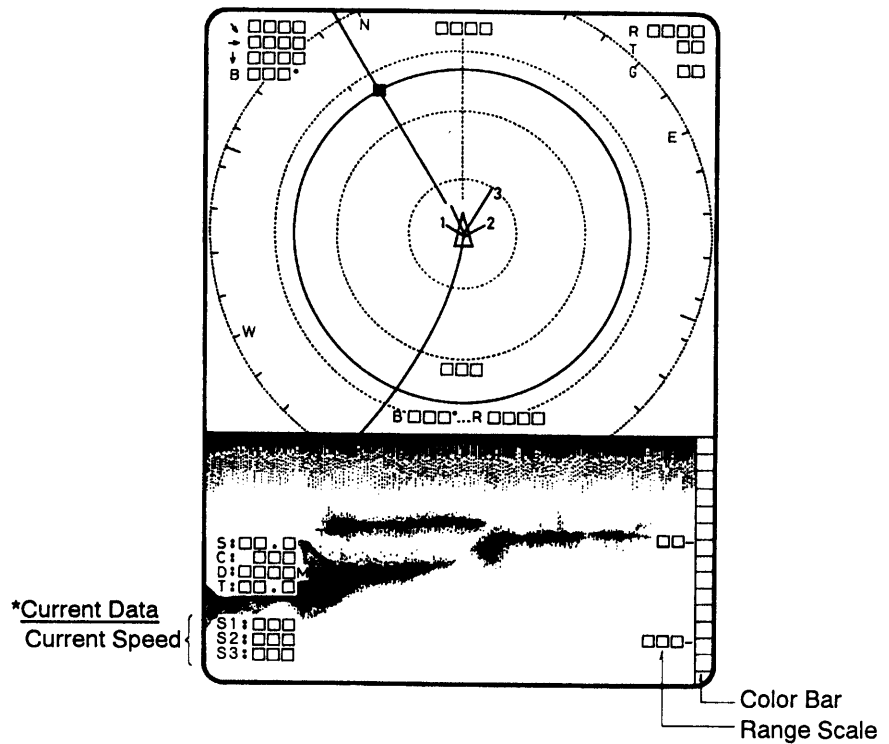


Figure 4-3 Marks and data appearing in the echo sounder display mode



## History display



\*Requires external sensor.




Figure 4-4 Marks and data appearing in the history display mode

## Permanently Displayed Marks and Data



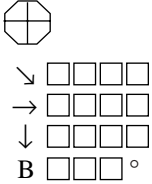
\*Requires external sensor.

Mark/Data	Description
Trackball Mark Data ↘ □□□□ → □□□□ ↓ □□□□ B □□□°	Trackball mark data: ↘ : Slant range → : Horizontal range ↓ : Depth B : Bearing  Bearing is shown in 360° or ±180° indication system, relative to ship's heading. In the latter case, "B" is indicated as follows: B□□□ P.... on the port side B□□□ S.... on the starboard side
Range Data R □□□□	Shows the range scale set with the RANGE control.
Tilt Angle Data T □□° ( □□ )	The tilt angle appears below the range. The tilt angle can be changed in 1° steps within the range of -5° to 60°. In *target lock and automatic tilt control, the instantaneous tilt angle appears in parentheses. Accordingly, both are equal when target lock is on. In automatic tilt, the upper indication shows the tilt angle set by the TILT lever and the lower indication the instantaneous tilt angle at which the sonar actually works.








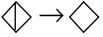
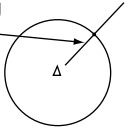

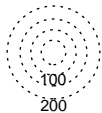
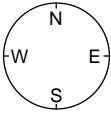
(Continued on next page)

Mark/Data	Description
Own Ship's Mark 	Shows own ship's present position. The direction of the arrow shows ship's heading. This mark moves with ship's movement in the * true motion mode. On all other modes it is fixed at the screen center.
* North Mark (or Heading Mark) 	When the CSH-23/24 is connected to a gyrocompass the mark is called the north mark and points North. If there is no gyrocompass input it is the heading mark and points in the direction of own ship's heading.
Heading Data	This data requires gyrocompass input. Bearing is displayed in 32-azimuth (N, N/E, etc.). Bearing can also be displayed in figures (for example, "360") by calling up the SYSTEM menu and selecting BRG READOUT-Course.
Trackball Mark 	Sets own ship's mark location for off-center display; sets location for mark input. The trackball (or arrow keys on the remote control box) controls this mark.



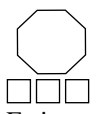
## Erased Marks and Data

Mark/Data	Description
Latest Event Mark  Event Mark 	These marks depict important locations. With speed log and gyrocompass connection these marks follow ship's movement. In the *true motion mode they are stationary. Ten marks, one latest and nine event marks, can be entered. When more than ten marks are entered the oldest is erased to make room for the latest.
Latest Event Mark Data 	The position data of the latest event mark, that is, horizontal range (→), current depth (↓) and bearing. (□□□□) shows the latest event mark's original depth, and remains unchanged regardless of ship's movement or tilt angle. When the event mark is erased the above data disappears from the screen. To erase an event mark, place the trackball mark on the event mark and press the EVENT key.

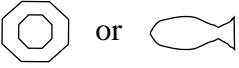

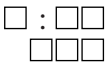


(Continued on next page)

Mark/Data	Description
<p>Latest Fish Mark</p>  <p>Fish Mark</p>  <p>Fish Mark</p> 	<p>These marks are inscribed on the screen by pressing the FISH key. Ten fish marks can be entered. Each time the key is pressed the fish mark appearance changes on the screen as follows:</p> <p>1st press of FISH key </p> <p>2nd press of FISH key </p> <p>3rd press of FISH key </p> <p>4th press of FISH key </p>
<p>Fish Movement</p>  <p>→ □□□□</p> <p>C □□□</p> <p>S □□.□</p>	<p>Fish movement from the fish speed mark (◊) to the latest fish mark (◊) is shown by distance, course (C) and speed (S) at the lower right corner of the screen.</p>
<p>Bearing and Range Marks</p>  <p>Range and Bearing Mark Data</p> <p>B□□□° R□□□□</p>	<p>These marks are used for monitoring echoes through the loudspeaker and also for displaying horizontal slice picture. If the *target lock function is on the bearing marks follow the movement of the target lock mark.</p> <p>This data appears when the bearing and range marks are displayed.</p>
<p>Heading Mark</p> 	<p>The heading mark is drawn with a dotted line. *Heading mark data appears at the top of the screen.</p>
<p>Range Rings</p> 	<p>The range rings are inscribed at intervals of 1/4 of the range in use. Range ring data is also provided every two range rings. The range ring interval can be changed from 1/4 to 1/2 through the menu.</p>
<p>Electronic Bearing Scale</p> 	<p>The electronic bearing scale is available with gyrocompass connection. It rotates with own ship's movement.</p>

(Continued on next page)



Mark	Description
<p>*Ship's Track Mark</p> 	<p>With gyrocompass or speed log connection, own ship's track is plotted by a solid line. When the length of the line exceeds five times the range the oldest part of the track is erased.</p>
<p>*Tidal Current Mark</p>  <p>Tidal Current Data Normal mode</p> <p>C1 : <input type="checkbox"/><input type="checkbox"/> <input type="checkbox"/><input type="checkbox"/> <input type="checkbox"/><input type="checkbox"/> M C2 : <input type="checkbox"/><input type="checkbox"/> <input type="checkbox"/><input type="checkbox"/> <input type="checkbox"/><input type="checkbox"/> M C3 : <input type="checkbox"/><input type="checkbox"/> <input type="checkbox"/><input type="checkbox"/> <input type="checkbox"/><input type="checkbox"/> M</p> <p>Combination mode</p> <p>C1 : <input type="checkbox"/><input type="checkbox"/> C2 : <input type="checkbox"/><input type="checkbox"/> C3 : <input type="checkbox"/><input type="checkbox"/></p>	<p>This mark can be displayed with current indicator input. The tidal current marks are displayed on the net shooting mark (▽) and net sonde marks (▽ ▽ ▽). The tidal current markers shows tidal current speed in three layers (1—3) selected on the tidal current indicator. The tidal current speed is shown by the length of the tidal current mark. Note however that no tidal current mark appears if the tidal current speed is less than 0.2 kts. Current direction can be shown as "to" or "from" by selecting CURRENT VEC-Current Flow Dir on the USER menu. In the normalmode with text, speed, direction and depth of the current are shown for three layers (C1, C2, C3). In the echo sounder combination and history modes, only the speed appears (C1, C2, C3), on the echo sounder combination or history display.</p>
<p>*Net Sonde Data</p> <p>S1 : <input type="checkbox"/><input type="checkbox"/> S2 : <input type="checkbox"/><input type="checkbox"/> S3 : <input type="checkbox"/><input type="checkbox"/></p>	<p>When the net sonde is connected, the depth of the net sonde transmitters appears in the text window, echo sounder, or audio area.</p>
<p>Nav Data</p> <p>S : <input type="checkbox"/><input type="checkbox"/> . <input type="checkbox"/> C : <input type="checkbox"/><input type="checkbox"/> D : <input type="checkbox"/><input type="checkbox"/><input type="checkbox"/> T : <input type="checkbox"/><input type="checkbox"/> . <input type="checkbox"/></p> <p>Own Ship Data</p> <p><input type="checkbox"/><input type="checkbox"/>° <input type="checkbox"/><input type="checkbox"/> <input type="checkbox"/><input type="checkbox"/>N <input type="checkbox"/><input type="checkbox"/><input type="checkbox"/>° <input type="checkbox"/><input type="checkbox"/> <input type="checkbox"/><input type="checkbox"/>E</p>	<p>With appropriate sensors speed (S), course (C), water depth (D) and water temperature (T) can be displayed on the text window, echo sounder combination display and history display.</p> <p>With navigation input position can be displayed in latitude and longitude, in the normal mode only.</p>
<p>Estimate Mark</p>  <p>Estimate mark data</p>	<p>The estimate mark gives relative fish quantity. Press the ESTIMATE key. The estimate mark data appears below the mark. The fish amount is assessed as between 0 and 100, where if the mark is filled with the strongest echo color reddish brown, the amount is regarded as "100." The size of the estimate mark can be changed with MARK SIZE2-Estimate Mark on the SYSTEM menu.</p>

(Continued on next page)

Mark	Description												
Target Lock Mark 	The target lock mark automatically tracks the fish school selected by the operator. This function requires speed and gyrocompass inputs.												
Net Shooting Mark  Net Shooting Data 	Press the SHOOT key at the instant you shoot the net to display the net shooting mark on the display. The net shooting mark is drawn at own ship's position the moment the key is pressed and moves on the own ship's track mark with ship's movement. In addition to the mark, time elapsed and *distance run (in meters) appear from the time the key is pressed. The mark and its data remain on the screen until the SHOOT key is pressed again.												
Net Sonde Mark  (10 pts. max)	These marks appear on the *ship's track mark in order at set intervals, when a net sonde is connected. In the echo sounder combination mode they also appear in the echo sounder picture, showing depth of the net sonde transmitters with bars extending vertically from the marks.												
E/S Picture Advance Range Data 	Picture advance on the echo sounder combination mode automatically changes to ship's speed dependent (advance) rate from the moment the SHOOT key is pressed, provided there is speed log input. The E/S picture advance range data shows the distance between the right and left edges of the echo sounder picture window in the ship's speed dependent advance. Since the net length plus wire length set on the DATA SET menu is used as this distance data, the echograms obtained during casting the net are displayed just across the E/S window. Set net length and wire length on NET SONDE in the DATA SET menu.												
Control Setting	When the switches listed below are operated the new setting is noted at the top of the screen in larger characters for five seconds. The auto tilt width and auto scan width also appear upon turning on the AUTO TILT and AUTO SCAN functions. <table border="1" data-bbox="518 1400 1125 1624" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th data-bbox="518 1400 826 1444">Control, Display</th> <th data-bbox="826 1400 1125 1444">Control, Display</th> </tr> </thead> <tbody> <tr> <td data-bbox="518 1444 826 1478">RANGE R <input type="checkbox"/><input type="checkbox"/><input type="checkbox"/><input type="checkbox"/></td> <td data-bbox="826 1444 1125 1478">AUTO TILT <math>\pm</math><input type="checkbox"/></td> </tr> <tr> <td data-bbox="518 1478 826 1512">TILT T <input type="checkbox"/><input type="checkbox"/>°</td> <td data-bbox="826 1478 1125 1512">AUTO SCAN <math>\pm</math><input type="checkbox"/></td> </tr> <tr> <td data-bbox="518 1512 826 1545">GAIN G <input type="checkbox"/>.<input type="checkbox"/></td> <td data-bbox="826 1512 1125 1545">BRILL <input type="checkbox"/></td> </tr> <tr> <td data-bbox="518 1545 826 1579">TVG TVG <input type="checkbox"/>.<input type="checkbox"/></td> <td data-bbox="826 1545 1125 1579">DIM <input type="checkbox"/></td> </tr> <tr> <td data-bbox="518 1579 826 1612">TX TX <input type="checkbox"/>.<input type="checkbox"/></td> <td data-bbox="826 1579 1125 1612"></td> </tr> </tbody> </table>	Control, Display	Control, Display	RANGE R <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>	AUTO TILT $\pm$ <input type="checkbox"/>	TILT T <input type="checkbox"/> <input type="checkbox"/> °	AUTO SCAN $\pm$ <input type="checkbox"/>	GAIN G <input type="checkbox"/> . <input type="checkbox"/>	BRILL <input type="checkbox"/>	TVG TVG <input type="checkbox"/> . <input type="checkbox"/>	DIM <input type="checkbox"/>	TX TX <input type="checkbox"/> . <input type="checkbox"/>	
Control, Display	Control, Display												
RANGE R <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>	AUTO TILT $\pm$ <input type="checkbox"/>												
TILT T <input type="checkbox"/> <input type="checkbox"/> °	AUTO SCAN $\pm$ <input type="checkbox"/>												
GAIN G <input type="checkbox"/> . <input type="checkbox"/>	BRILL <input type="checkbox"/>												
TVG TVG <input type="checkbox"/> . <input type="checkbox"/>	DIM <input type="checkbox"/>												
TX TX <input type="checkbox"/> . <input type="checkbox"/>													
Color Bar	The 16-color bar appears at the right-hand edge in the echo sounder and history displays.												
E/S Range Scale	The range scale for the echo sounder picture appears in the echo sounder combination mode. You can display it on the right or left side of the screen by selecting ES/NET REC on the INIT SET/TEST menu.												

# MENU OVERVIEW

Many functions are carried out through the menu system, which consists of the USER, SYSTEM, DATA SET and INITIAL SET/DATA menus. The menu you will use most often is the USER menu.

Menu	How to open
USER	Press MENU.
SYSTEM	Press  and MENU together.
DATA SET	Press  and MENU together.
INIT SET/TEST	Press MENU and ON together. (Press and hold down until the buzzer sounds. All LEDs light while keys are held down.)

## USER Menu Operation

The menu operating procedure is the same for all types of menus. Below is the basic menu operating procedure for the USER menu.

1. Press the MENU key to open the USER menu.

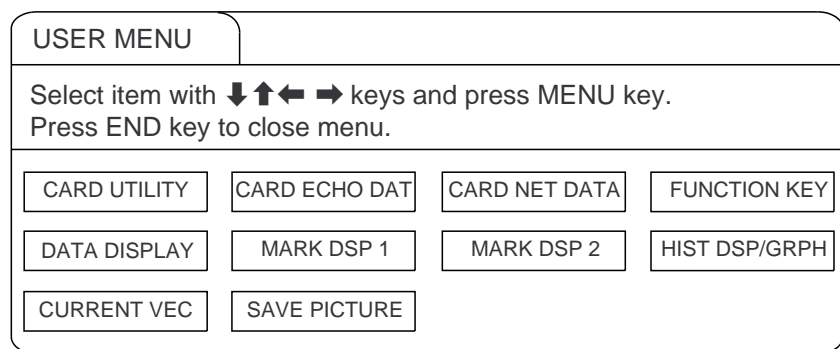
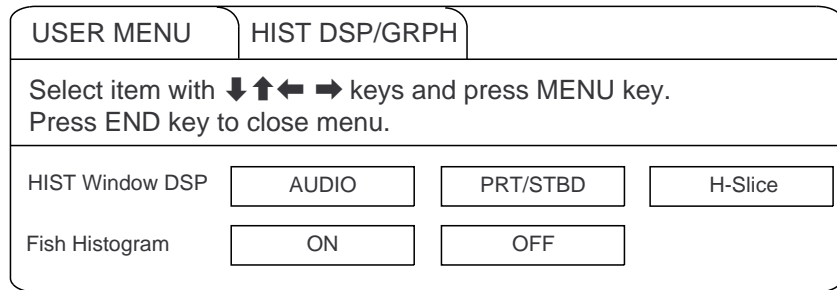


Figure 5-1 USER menu

2. Operate the arrow keys in sub panel 1 to select a menu. As you move through the menu, each item, initially shown as blue on gray, reverses to gray on blue to show selection. For example, select the HIST DSP/GRPH menu.
3. Press the MENU key to display menu selected.



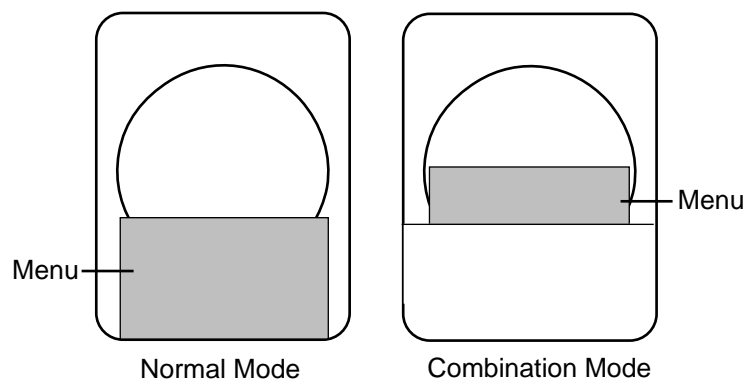
*Figure 5-2 HIST DSP/GRPH menu*

4. Operate the up and down arrow keys in sub panel 1 to select menu item, and the right and left arrow keys to select option.
5. Press the END key to close the menu. Press the key again to display picture.

**Note:** The HELP key provides menu operating information.

### Menu screen location and display mode

Menu screen location depends on display mode as shown in the figure below.



*Figure 5-3 Menu screen location and display mode*




# USER Menu Description

*Table 5-1 User menu description*

Menu	Menu Item	Description
CARD UTILITY	List	Lists contents of memory card.
	Save	Saves control and menu settings to memory card.
	Delete	Deletes data from memory card.
	Initialize	Formats memory card.
CARD ECHO DAT	Save	Saves echo inside estimate mark (stored in internal memory by MEMO key) to memory card.
CARD NET DATA	Save	Saves net shooting data (stored in internal memory) to memory card.
FUNCTION KEY	Register	Saves customized settings of range, gain, display mode, TX ON/OFF, user menu, system menu, and data set menu to function key.
DATA DISPLAY	Event Mark 1 Event Mark 2 Fish Mark On Track Data Text Window ES Window	Turns those marks on/off. "ES Window" selects tidal current data or net sonde data, which are displayed on the E/S combination display while shooting the net.
MARK DSP 1	Range/Bearing Heading Mark Range Rings Bearing Scale Auto Scan Width	Turns those marks on/off. Note that turning off Range/Bearing mark also turns off the data display.
MARK DSP 2	Ship's Track Net Movement Plot Fish MK Connect Fish Tracking MK Fish Track Plot	Turns those marks on/off.
HIST DISP/GRPH	HIST Window Dsp	Chooses type of display for HIST window: AUDIO: Displays echoes within audio sector. PRT/STBD: Displays echoes in specified port and starboard directions. H-Slice: Displays echoes along upper half of range mark.
	Fish Histogram	Turns on/off echo intensity distribution for echoes inside estimate mark on the Target Slice display.

*(Continued on next page)*



Menu	Menu Item	Description
CURRENT VEC	Own Ship Mark  w/Current Vec Own Position Mark  w/Current Vec Net Shoot Mark  w/Current Vec Current Flow Dir	Turns those marks on/off. Current Flow Direction displays tidal current direction as "To" or "From".
SAVE PICTURE	Save Method	Selects how to save echoes. Whole: Saves echoes and data on whole screen to memory card. Est MK: Saves echoes inside estimate mark to internal memory. QK Save: Saves echoes and data on whole screen to internal memory.

# SYSTEM Menu Description

The SYSTEM menu can be displayed by pressing MENU and  together.

For help, press the HELP key.

Menu	Item	Description
SIGNAL PROCESS	Smooth Echo Rng	Selects echo smoothing level in range direction. The higher the number, the higher the smoothing effect. The setting range is from 0 to 3.
	Smooth Echo Cir	Selects echo smoothing level in circular direction. The higher the number, the higher the smoothing effect. The setting range is 0 to 3.
	Delete Color	You can delete undesired echoes and noise in certain colors from the display. This is useful for eliminating noise and detecting large fish schools. The setting range is 0 to 10. If you want to delete echoes displayed in colors weaker than the 5th weakest color, for example, set to 4.
FAR TVG	Far TVG Curve	Selects suitable FAR TVG curve to compensate for propagation loss of sound at 100 m or farther. 30log is the normal setting. 25log: Suitable for searching small bottom fish in shallow water or near coastline. 30log: Standard setting 35log: Select for long distance searching in low sounding frequency. 40log: Use this setting when long range gain higher than 35log is required.
TM DSP	External KP Sync	Not used. If you wish to synchronize transmission with a keying pulse of other sonar to reject interference, set transmission cycle to "0" on data setting window.
	TM Display Range	Selects a display range in the true motion display. The options 1.3R and 1.6R determine how many times the display range is expanded from the range in use.
TARGET LOCK	Tracking Method	This option determines what item to track in target lock; target lock mark, fish echo or Auto.
	Tracking Echo Color	Select the weakest color to track in the target lock function.
	Fish Speed Limit	Sets limit speed (kt) for tracking of fish. When speed of fish exceeds limit set here target lock is cancelled.
	Fish Track Window	Selects range (1 to 10m) out of tracking window. When fish tracks out of this window the equipment judges the target is moving and traces its track. 10 is the normal setting.

(Continued on next page)

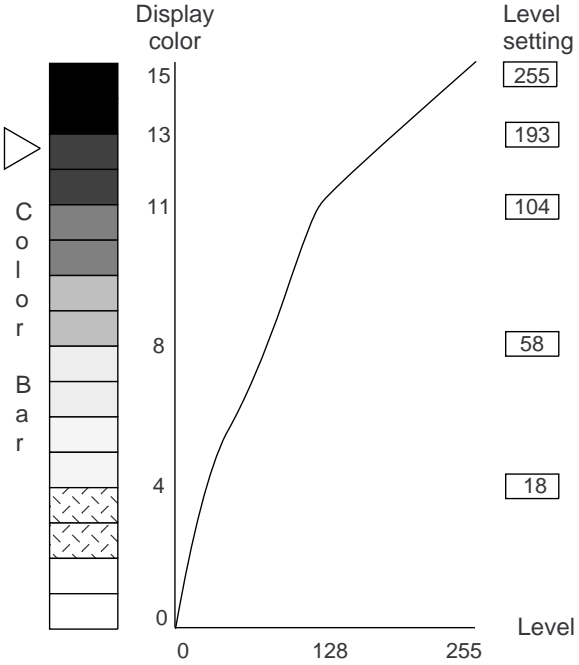
<b>Menu</b>	<b>Item</b>	<b>Description</b>
TARGET LOCK	Fish Spd Update	Selects update interval of fish speed readout. You can select from 15 seconds, 30 seconds, 45 seconds, or 60 seconds. 60 is the normal setting.
	Target LK Window	Selects size of target lock window (in pixels); 64 x 64 (normal), 96 x 96 (large), or 128 x 128 (largest).
BRG READOUT	Course	Selects unit of readout for course and bearing between fish marks; 32 compass bearing or 360° true bearing.
	Current Data	Displays current data readout in 32 compass bearing, 360° true bearing, 180° relative bearing, or 360° relative bearing.
	Event Mark	Displays event mark readout in 32 compass bearing, 360° true bearing, 180° relative bearing, or 360° relative bearing.
	Other Marks	Displays location of trackball mark and bearing marker in 32 compass bearing, 360° true bearing, 180° relative bearing, or 360° relative bearing.
DATA DISPLAY	Control Setting	Keep OFF for normal operation. "Sonar" and "TGT Lock" options are for factory use only.
	Text Window Data	Chooses (external sensor) data to display at screen bottom. "1" provides all available data. Other options provide less data in larger characters.
MARK SIZE 1	Trackball Mark	Select size and shape of trackball mark; + mark, or rectangle, available in large or small size.
	Target Lock Mark Event Mark 1 Event Mark 2 Fish Mark Own Ship Mark	You can select the size of these marks for large or small.
MARK SIZE 2	Own Ship Mark Net Shoot Mark Estimate Mark	Select the size of these marks for large or small.
	Current Vector	Selects the length of the current vector for long or short.
	Range Rings	Selects interval (times range in use) of range rings; 1/4R or 1/2R.
	Ship's Track MK	Chooses length (times range in use) of ship's track.

*(Continued on next page)*

<b>Menu</b>	<b>Item</b>	<b>Description</b>
ES/NET REC	ES 1 Color Curve	Selects echo level versus presentation color curve for echo sounder 1. Linear: Weak echoes are not as conspicuous as in log setting. Useful for eliminating weak echoes. Log: Weak echoes are painted in "stronger" colors. The higher the setting the easier are weaker echoes to see on the display.
	ES 2 Color Curve	Same as above except for echo sounder 2.
	Picture Advance	Sets picture advance speed for the echo sounder display.
	Advance at Shoot	Chooses "Sonde" to have ship's speed dependent advance of echo sounder picture while shooting net and "KP" to have advance synchronized with transmission.
	Net Rec Picture	Selects net recorder picture display mode; up/down or down sounding.
HIST DISPLAY	H-Slice Width	Selects width for sampling echoes along upper half of range marker in horizontal slice display. The higher the setting the wider the sampling area.
	PRT/STBD Sample	Sets angle from ship's bow for sampling echoes in PRT/STBD display.
INTERLOCK	Tilt, Range Event Mark Fish Mark Net Shoot Mark Target Lock	You can interlock these items with respective items on sonar connected to the CSH-23/24. If you interlock the range, for example, anytime the range is changed on the CSH-23/24 it is automatically changed on the sonar connected and vice versa.
DEFAULTS	Defaults	Press MENU key to clear all user, data set and system menus settings and restore default settings on all system menus.

# DATA SET Menu Description

The DATA SET menu can be displayed by pressing MENU +  $\blacklozenge$ . For help, press the HELP key.

Menu	Item	Description
COLOR CURVE	Sonar 1 Sonar 2 Echo Sounder 1 Echo Sounder 2	<p>For each of these devices you may change settings of echo level versus presentation color curve, which you selected at either "CURVE" at SIGNAL PROCESS on data setting window or system menu. Note that Sonar 2 is not used.</p> <p>1. First select item to change on COLOR CURVE sub menu, and then press the MENU key.</p>  <p>2. Color curve can be changed at colors no. 4, 8, 11, 13 and 15. Press up or down arrow key to set cursor on color no. you want to change curve.</p> <p>3. Press the right or left arrow key to change value.</p> <p>4. Press the MENU key to terminate color curve setting. Then, the display shown below appears. Follow the instructions on the screen.</p> <p><i>Color curve setting is completed. To save change and close the menu, press MENU key. To cancel change and close the menu, press END key.</i></p>

(Continued on next page)

Menu	Item	Description
CHANGE COLOR	Sonar 1 Sonar 2 Echo Sounder Marks Menu	<p>You can customize the color of these items according to user request, etc. Note that Sonar 2 is not used. For display color change on Sonar 1 you can change color according to selection by COLOR key.</p> <p>1. First select item to change on CHANGE COLOR sub menu, and then press the MENU key.</p> <div data-bbox="853 533 1380 963" data-label="Figure"> </div> <p>2. Using the arrow keys, place the cursor on color segment you want to change color. If you are changing the color of marks or the menu, press the HELP key to display guidelines for changing their colors.</p> <p>3. Press the up or down arrow key to change value, between 0 and 100. You can press and hold down the key to get faster change.</p> <p>4. Repeat steps 2 and 3 to change other colors.</p> <p>5. Press END key to terminate color setting. Then, the display shown below appears. Follow the instructions on the screen.</p> <p><i>Color curve setting is completed. To save change and close the menu, press MENU key. To cancel change and close the menu, press END key.</i></p>

(Continued on next page)

<b>Menu</b>	<b>Item</b>	<b>Description</b>
NET SHOOT PLAN	Net Diameter	Sets estimated ship's turn diameter necessary for shooting net, to get accurate depiction of net location mark, which you can display by pressing the NET COURSE key. The setting range is 200 to 1000 meters in 10 meter steps.
	Tilt Interlock	Choose ON to interlock diameter of net location mark with tilt angle. When you lower the tilt angle the on-screen net location mark enlarges. (For example, the net diameter is set for R meters. When the tilt angle is 45° the diameter of the on-screen net is 2 R meters.)
NET SONDE	Net Sonde XMTR	Sets number of net sonde transmitters and their distances between each other.
	Net Length	Sets net length. The setting range is 500 to 3000 meters in 100 meter steps.
	Wire Length	Sets wire length between own ship and net. The setting range is 100 to 1000 meters in 100 meter steps.
	Net Width	Sets net width. The setting range is 0 to 100 meters.
NET PLOT CORR	Layer 1 Layer 2 Layer 3	The movement of the net during net shooting is plotted by using water current speed and direction fed from external sensor. The external sensor feeds that data for three depths (layers), thus net movement will be different at each layer. Determine degree of difference among layers considering net, sea conditions, vessel construction, etc. If 50% is set, for example, on-screen net moves at speed of 50% of water current speed.




# INIT SET/TEST Menu Description

The INIT SET/TEST menu can be display by pressing MENU and ON together.

Menu	Item	Description
HEADING ADJ	Heading Adjust	Sets deviation angle of HEAD mark on hull unit from ship's bow. If deviation is 15° to port, enter "15" (degrees); 15° to starboard, enter "345."
BAUD RATE	I/F CS-120A Aux Port 1 Aux Port 2 Aux Port 3 NMEA	Set data transmission speed (baud) of ports. Set to 2400 bps for I/F CS-120A.
EXT KP	Ext KP Polarity KP Out Polarity	Choose positive or negative logic for keying pulse fed from external sonar or echo sounder, to synchronize transmission.
UNIT/ LANGUAGE	Depth	Chooses unit of depth readout.
	Dist for Shoot	Chooses unit of distance run readout for shooting net; meters, feet, fathoms, or passi.
	Temperature	Chooses unit of water temperature readout; centigrade or fahrenheit.
	Language	Chooses language used in menu; English, Japanese, or Korean.
SELF TEST	Single	Performs display unit self test once.
	Continuous	Performs display unit self test continuously.
	Panel	Checks the keys of the display unit and remote control box for proper operation.
	Color	Checks for proper display of colors.
	Gray	Checks for screen distortion with gray test.
	SIO	Conducts communication test between the display unit and transceiver unit. Requires a test plug.

*(Continued on next page)*



<b>Menu</b>	<b>Item</b>	<b>Description</b>
ECHO TEST	Display Test	Checks the display unit without connection of other units. A test pattern is displayed.
	Demonstration	Reserved for future use.
E/S NET REC	E/S Audio Scale	Displays depth scale on right or left side of echo sounder display.
	ES Draft Adjust	Sets ship's draft to read true depth on echo sounder display.
	ES 2 Select	Selects equipment connected to ES 2 port; echo sounder or net recorder.
	Net Rec Range	Sets sounding range of net recorder transmitter unit.
DEFAULTS	Defaults	Restores default settings.
	Program Recalls	Reserved for future use.
OTHERS	EVENT KEY 	EVENT: The EVENT  key functions to inscribe event mark. SHOOT: The EVENT  key functions as the SHOOT key on the remote control box to display net shooting mark.
	Data Format	Input data format can be selected among CIF, NMEA0183 Ver.1.5* and NMEA Ver.2.0*.
	Auto Tilt	Auto tilt can be selected, wide or narrow*.

\* Under development

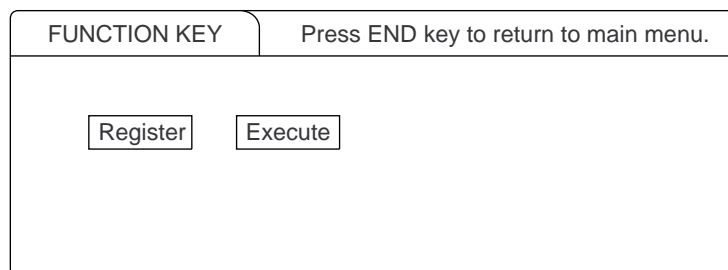
# FUNCTION KEYS

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Similar to the quick dialing function on a telephone, the five function keys (F1–F5) on the main panel record control and menu settings and replay them back exactly as programmed. The items you can program are gain, display mode, TX ON/OFF, USER menu, SYSTEM menu, DATA SET menus and data setting window. The function keys are useful for quickly setting up the sonar for a specific purpose such as seabed detection.

## Programming the Function Keys

1. Tune the sonar as desired (control panel, data setting window and menu).
2. Press the MENU key.
3. Select the FUNCTION KEY sub menu and press the MENU key.



*Figure 6-1 FUNCTION KEY menu*

4. Press the MENU key again to register.
5. Select the FUNCTION key to program by  $\blacktriangle$  or  $\blacktriangledown$  key.
6. Press the MENU key. It takes about one minute to save settings.

## Replaying a Function Key

Press function key (F1–F5) desired for 2 seconds.

**Note:** When the power is removed with a function key active, the unit starts up with previous settings regardless of function key's original setting. For example, the range setting of function key F1 is 600 meters. If the range is changed to 800 meters before the power is removed, the unit starts up with the range set to 800 m. To restart operation with F1's original setting, turn F1 off and on.

## Saving Function Key Settings to a Memory Card

1. Press the MENU key to display the USER key.
2. Select the CARD UTILITY menu.

CARD UTILITY		Press END key to return to main menu.
List	Execute	
Save	Execute	
Delete	Execute	
Initialize	Execute	

*Figure 6-2 CARD UTILITY menu*

3. Select Save and press the MENU key.

**Note:** If the card has not been initialized, initialize it by selecting Initialize.

## Replaying Function Key Settings from a Memory Card

Press the CARD REPLAY key on sub panel 1.

**Note:** When function key settings are replayed from a memory card, current settings on all function keys are erased. Therefore, if necessary, save current function key settings to another memory card before replaying.

# ADVANCED LEVEL OPERATION

## Finding Fish School Center

When you want to find the center depth of a fish school, use the auto tilt function, which automatically scans the tilt angle within the selected width. There are two automatic scan range, WIDE and NARROW, which can be selected by the INIT SET/TEST menu.

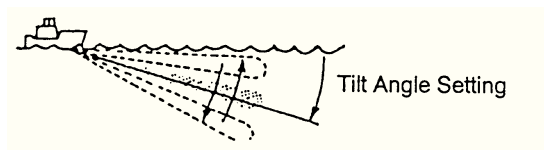
**Note:** NARROW in under development.

*Table 7-1 Automatic scan range at menu setting WIDE of OTHER/INIT SET/TEST menu*

Range (m)	Width (1)	Width (2)	Width (3)	Period
60, 100	±10°	±16°	±20°	every 6 transmissions
150, 200	"	"	"	every 4 transmissions
300, 400	"	"	"	every 2 transmissions
500, 600	±8°	"	"	"
800	±6°	±12°	±16°	"
1000	±4°	±8°	±12°	"
more than 1200	±2°	±4°	±6°	"

For example, when the RANGE control, TILT lever and WIDTH key are set to 800 m, 8° and width (1), respectively, the tilt angle varies at every transmission as follows:

8° → 8° → 10° → 10° → 12° → 12° → 14° → 14° → 12° → 12° → 10° → 10° → 8° → 8° → 6° → 6° → 4° → 4° → 2° → 2° → 4° → 4° → 6° → 6° → 8° → 8°



*Figure 7-1 Tilt angle setting*

*Table 7-2 Automatic scan range at menu setting NARROW of OTHER/INIT SET/TEST menu*

Range (m)	Width (1)	Width (2)	Width (3)
60, 100	±4°*	±6°*	±8°*
150, 200	±2°	±4°*	±6°*
300, 400	±1°	±2°	±4°*
500, 600	"	"	±3°
800	"	"	"
1000	"	"	"
more than 1200	"	"	"

**Note:** Period equals one transmission.

Tilt angle changes in 2° steps for asterisk-marked width; 1° steps for all other widths.

### How to find fish school center

1. On sub panel 1 or the remote control box, turn on the AUTO TILT key. The lamp above the key lights on sub panel 1.
2. With the WIDTH key, select scanning width. Auto tilting begins, with tilt angle set with TILT lever as a center tilt angle. Successively changing tilt angle is displayed in parentheses at the upper right of the screen.
3. To change center tilt angle, operate the TILT lever.

## Tracking a Fish School

The target lock function automatically tracks an important fish school so that you won't lose sight of it on the display screen. Three types of target lock are available: Target Mark, Fish or Auto. One may be selected on the SYSTEM menu. This function requires speed and heading inputs.

### Target mark tracking

Target mark tracks the target lock mark which is plotted on a fish school. For example, in the figure below the target lock mark is placed on target E. Then, the CSH-23/24 remembers the location of E and automatically changes the tilt angle as the ship moves from A through D so as to keep the location within the sonar beam. As long as fish school E is stationary its echo is kept displayed on the screen.

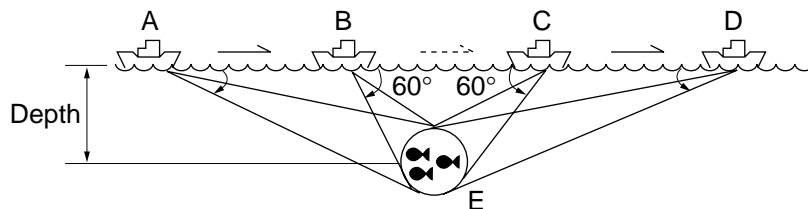


Figure 7-2 Target lock mark placed on fish school echo

**Note:** The target lock works up to a tilt angle of 60°. In the drawing above, the tilt angle is fixed at 60° between B and C. During this period, however, calculation is continuously being performed. When own ship comes to point C, the target lock function is resumed.

### Fish echo tracking

In the target mark tracking mode the tilt and distance are automatically changed to keep the target lock mark within the sonar beam. However, because the fish is moving, the sonar cannot track a moving echo. In the Fish echo tracking mode, however, the sonar automatically tracks the fish echo by calculation fish and own ship movements.

### Auto tracking

This mode automatically changes tilt in addition to the control of the Fish echo tracking mode.

### Using target lock

1. Select TGT Mark Fish or AUTO on the TARGET LOCK menu in the SYSTEM menu.
2. Operate the trackball to place the trackball mark on fish school you want to track.
3. Press the TARGET LOCK key to light the lamp above it. The target lock mark (⊙ or 🐟) appears on the fish school and tracking begins. If the target mark disappears, start from the beginning.
4. To delete the fish school's track and quit the target lock, open the sub panel 2 and select DELETE MK/TRACK followed by pressing + or - key.

**Note:** There are several preset parameters for “Fish” target lock on the SYSTEM menu. See the SYSTEM menu description in Chapter 5.

## Target lock mark data

The following marks and data appear while the “Fish” target lock is in operation.

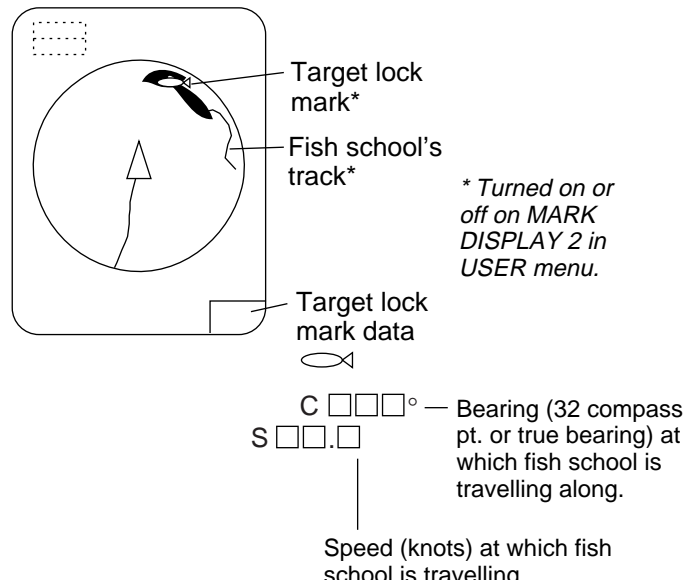


Figure 7-3 Target lock mark data

## Target lock mark appearance

The size and thickness of the target lock mark indicates size and tracking status:







Target lock mark appearance	Meaning
Fast  Medium  Slow 	Mark size indicates relative speed. Faster than 2 kt 1 to 2 kt Less than 1 kt
  	Mark thickness shows tracking status. The number of Tx cycles for missing the target. 0 to 5 times 6 to 10 times 11 to 20 times Mark disappears when more than 21 Tx cycles occurs.

Figure 7-4 Target lock mark appearance

## Detecting Fish Schools Aurally

Sometimes you may be preoccupied with other tasks and unable to concentrate on watching the sonar picture. In such cases it would be a good choice to use the audio function. This function enables you to monitor echoes from fish schools and seabed through the built-in speaker.

After you've become accustomed to monitoring fish aurally, you should be able to detect a fish school from a range longer than you can detect it on the screen. In addition you may judge whether the fish school is approaching or going away; the tone becomes higher when the school is approaching and lowers when the school is going away.

1. Operate the trackball to place the trackball mark to the direction you want to monitor through the speaker.
2. Press the R/B key. The bearing mark appears on the display. Echoes in a 30°, 60°, 90°, 180° or 330° sector centering the bearing mark are monitored through the speaker. You can adjust speaker volume with the AUDIO control.
3. To change coverage area, open the data setting window (sub panel 2) and change width of AUDIO SECTOR.
4. To scan the coverage area, open the data setting window, turn on AUTO SCAN and set scanning WIDTH.

**Note:** You can display the signal monitored through the loudspeaker on the history display combination window by pressing the HIST key, if AUDIO is selected on the HIST Window DSP menu in the USER menu.



# The Fish Alarm

The fish alarm sounds an audible alarm when a fish echo above a preset strength enters an alarm zone. You set parameters for the fish alarm at ALM on the data setting window (sub panel 2).

**ON/OFF:** Turns alarm on or off.

**Level:** Sets echo strength level which will activate the alarm.

**Zone:** Sets alarm zone.

1. Open the data setting window and select ALM•AUDIO.
2. Press the + key of the ZONE item.
3. Operate the trackball to place the trackball mark on the starting point of the alarm zone.
4. Press the + key.
5. Rotate trackball clockwise to select the end point. The display paints a fan-shaped alarm zone.
6. Press the + key.

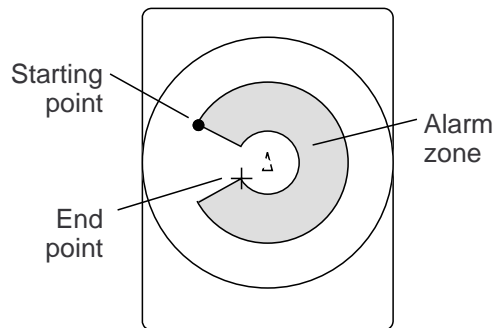
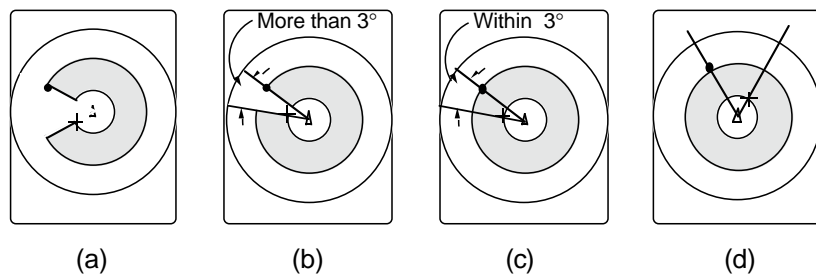


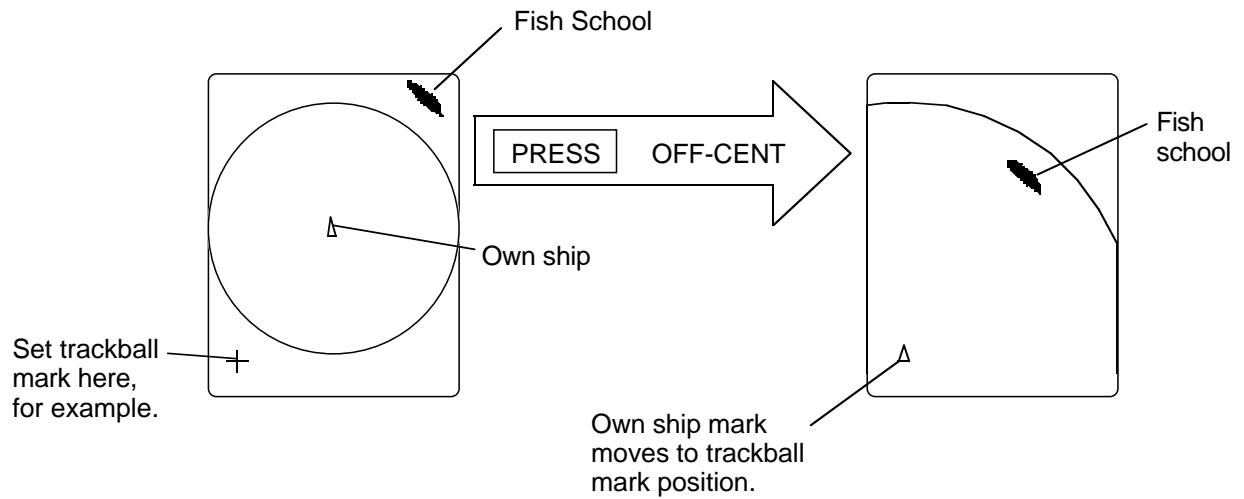
Figure 7-5 How to set the fish alarm zone

**Note:** There must be at least three degrees difference between the starting and end points to get a fan-shaped alarm zone as shown in (a) and (b). Otherwise, the unit paints a 360 degree alarm zone as in (d).



# Relocating Fish School for Easy Observation

1. Operate the trackball to place the trackball mark on the position where you want to relocate the own ship mark.
2. Press the OFF-CENT key.
3. To move the own ship mark back to the screen center, press the OFF-CENT key again.



*Figure 7-6 How to relocate fish schools*

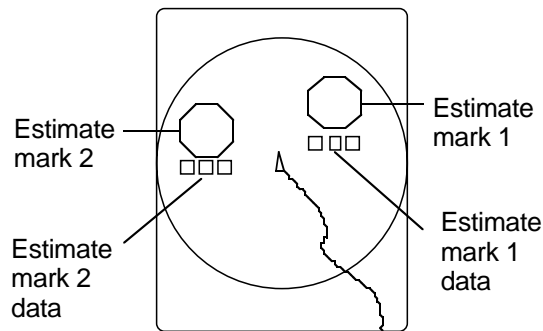
# Comparing Fish School Concentration

You can get an estimate of the volume of two fish schools by using the two ESTIMATE keys.

1. Operate the trackball to place the trackball mark on a fish school, and then press the ESTIMATE 1 key.

The estimate mark appears on the fish school. Relative volume is shown by a figure between 0 and 100, below the estimate mark. When inside the mark is filled with reddish brown, volume figure is “100”.

2. Operate the trackball to place the trackball mark on another fish school and press the ESTIMATE 2 key.
3. Compare estimate figures for each fish school.
4. To turn off the estimate marks press their respective keys.

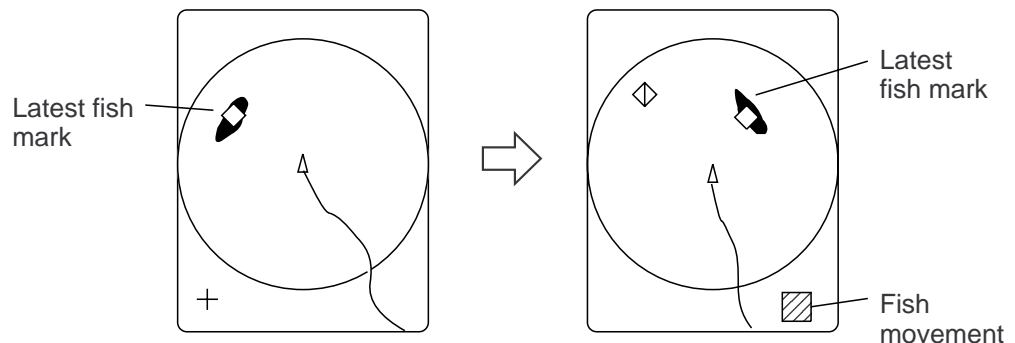


*Figure 7-7 Estimate marks and their data*

# Measuring Fish School Speed

To ensure a good haul, it is important to estimate the direction and speed of the fish school before shooting the net. You can do this with the FISH key. With tidal current data plus fish speed data, you can determine the timing of the net shooting more efficiently. This function requires speed and heading inputs.

1. Place the trackball mark on the center of a fish school, and then press the FISH key. The latest fish mark (◇) appears on the fish school.
2. Wait 1 to 2 minutes.
3. Place the trackball mark on the same fish school selected in step 1 and press the FISH key. The latest fish mark (◇) appears on the target and the 2nd latest fish mark (◇) appears on the location selected at step 1. At the bottom left corner of the screen, the distance between the two fish marks, and fish school course and speed appear.
4. If you want to delete fish marks and fish speed marks, open the data setting window, select DELETE MK and then press the FISH key.

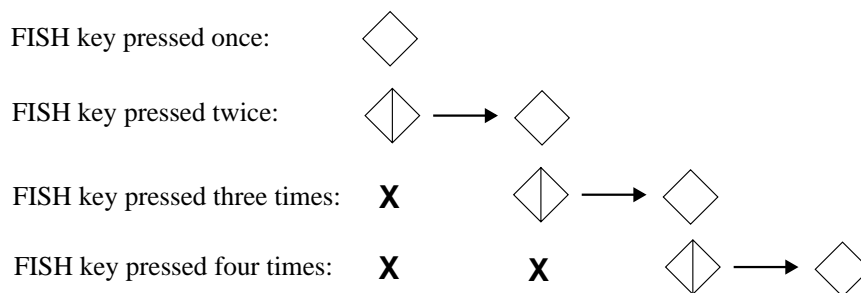


*Figure 7-8 How to measure fish school speed*

**Note 1:** Movement is calculated using ship's speed and bearing inputs. Accordingly, pitching and rolling may affect the calculation. For better results, try the procedure two or three times to verify reliability.



**Note 2:** The time and distance between pressings of the FISH key should be as long as possible to increase accuracy of measurement. For more accurate measurement repeat the procedure two or three times.

**Note 3:** Each time the FISH key is pressed the latest fish mark and ship's speed mark change in the sequence shown below:



## The Event Mark

The event mark is useful for finding the horizontal range, depth and bearing to a location some distance from current position. This function requires speed and heading inputs.

There are two types of event marks: event mark 1 and event mark 2. Ten of each type of mark can be entered. The latest event mark is displayed as  and  for event mark 1 and event mark 2, respectively. Older event marks are displayed by a cross plus event number (event mark 1) or an inverted Y with event number (event mark 2). When you enter more than ten event marks, the unit erases the oldest mark, one by one.

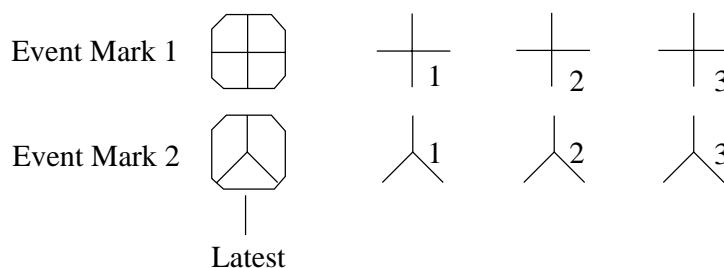
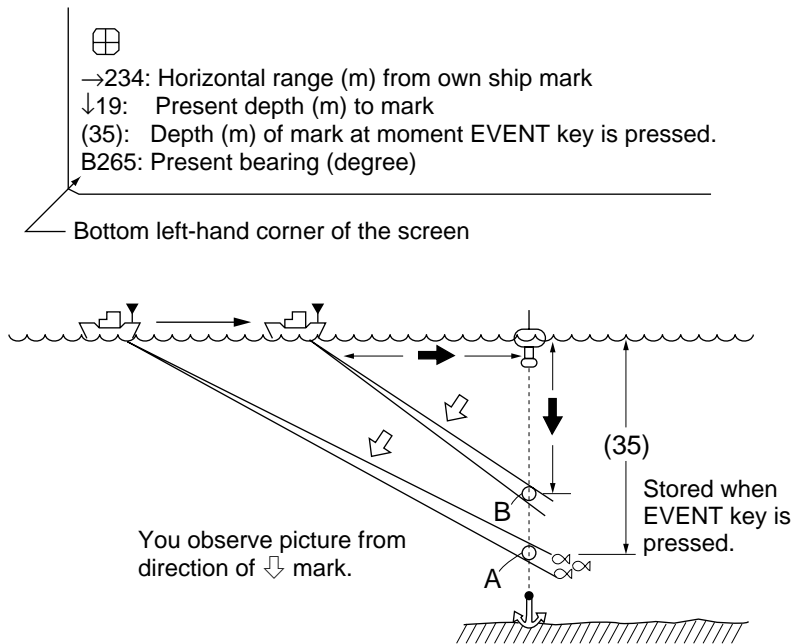


Figure 7-9 Appearance of event marks 1 and 2

### Entering an event mark

1. Set the trackball mark where you want to place an event mark (latest event mark).
2. Press the EVENT key. The horizontal range, depth and bearing to the event mark appear at the bottom left corner of the screen.



*Figure 7-10 Event mark description*

Plotting an event mark on the display is equivalent to dropping a buoy with an anchoring chain that extends from surface to bottom. The buoy is fixed at its geographical location, but the marker on the display moves to a point where present beam plane intersects the anchor chain of the buoy as ship moves or the tilt angle is changed. This can be said about other marks as well such as fish mark and trackball mark.

**Note:** This function requires speed and heading inputs.

### Erasing an event mark

Open the data setting window (sub panel 2) and select DELETE MK. Press appropriate EVENT key to erase mark.

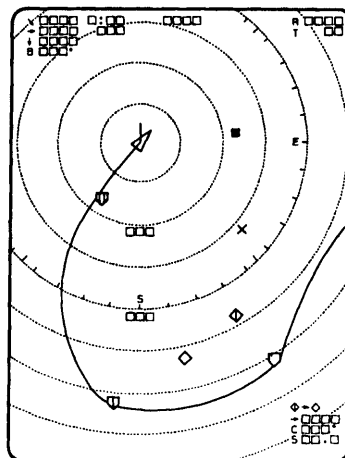
# True Motion Display

The relative motion display places the own ship mark at the screen center, and echoes from fish and the seabed move on the screen relative to own ship's movement. This means that even when the ship is dead in water, fish echoes move on the display.

In the true motion display, however, stationary objects are fixed and own ship and fish echoes move on the display in accordance with their true courses and speeds. Thus you can observe own ship and fish echo movement with respect to the seabed.

Open the data setting window and select SONR•BEAM. Set UP/TM in the SONAR menu to TM. This function requires speed and heading inputs.

Although the true motion mode is available for use in all modes, use in the combination modes is not recommended since the own ship mark may move into the combination picture area.

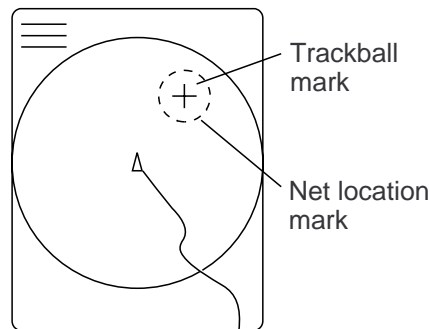


*Figure 7-11 True motion display*

## Plotting Net Location Mark

Before shooting the net, you will decide the shoot timing considering the water current direction, distance to fish school and moving direction of the fish school. Use the net location mark as a guide to decide the timing. This function requires speed and heading inputs.

1. Place the trackball mark on the fish school to be caught.
2. Press the NET COURSE key. The net location mark is depicted by a dotted ring with a diameter equivalent to that of your purse seine net, being centered on the trackball mark.



*Figure 7-12 Net location mark*

3. To adjust the location of the net location mark, move the trackball mark.
4. Press the NET COURSE key again. The dotted ring is replaced by a solid ring and the lamp above the NET COURSE key lights.
5. To erase the mark, press the NET COURSE key again.

You can adjust the diameter of the net location mark on NET SHOOT PLAN in the DATA SET menu.



# Observing Net Behavior

With net sonde connection you can observe net behavior after the throwing of the net, on the echo sounder combination mode. Accurate depiction of net sonde position depends on proper setting of the distances between net sonde transmitters. You can set those distances on NET SONDE XMTR in the DATA SET menu.

This function requires speed and heading inputs.

1. Press the SHOOT key just upon throwing the net into the water.

Then, the net shooting mark (◻) appears at the own ship mark and also at the right edge of the echo sounder picture. Afterwards, whenever a net sonde transmitter on the net is thrown into water, a net sonde mark appears on own ship mark and moves with ship movement. The depths of the net sonde transmitter units are digitally displayed at the lower left of the screen after the receiving transducer is placed into water. The net sonde marks appear also on the echo sounder picture as below, where the length of the vertical lines show the depth of the net sonde transmitter unit.

2. To erase the net sonde mark and associated data, press the SHOOT key again.

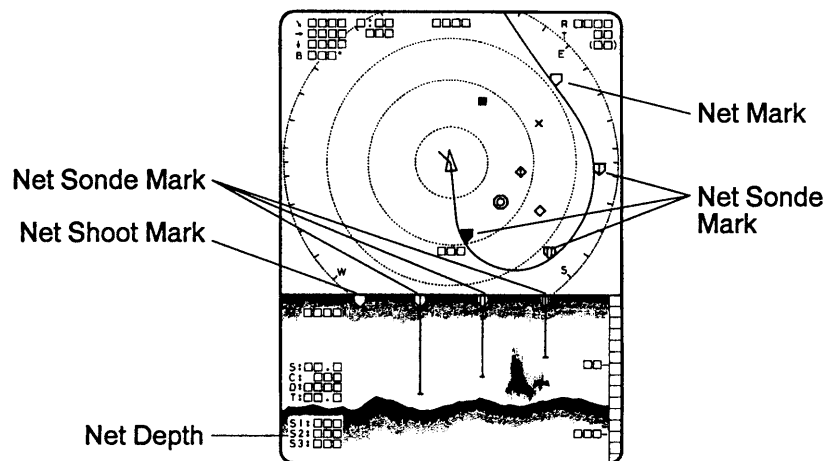


Figure 7-13 Net behavior

# Target Slice Display

Using automatic tilting, the target slice mode displays the echo inside the estimate mark at several different tilt angles (depth). To access the target slice display, press the TARGET SLICE key. The table and illustration below describe the target slice mode.

No. in Drawing	Display Information	Applications
①	Echoes inside estimate mark.	Show expanded view of fish echoes.
②	Bar graph display of echo signal level distribution for echoes inside estimate mark.	Expected to be useful for estimating fish species since bar graph characteristics may be different with fish species.
③	Echoes inside estimate mark at different tilt angles (depth).	This presentation gives a three-dimensional view of a fish school to help judge vertical distribution of the fish school.

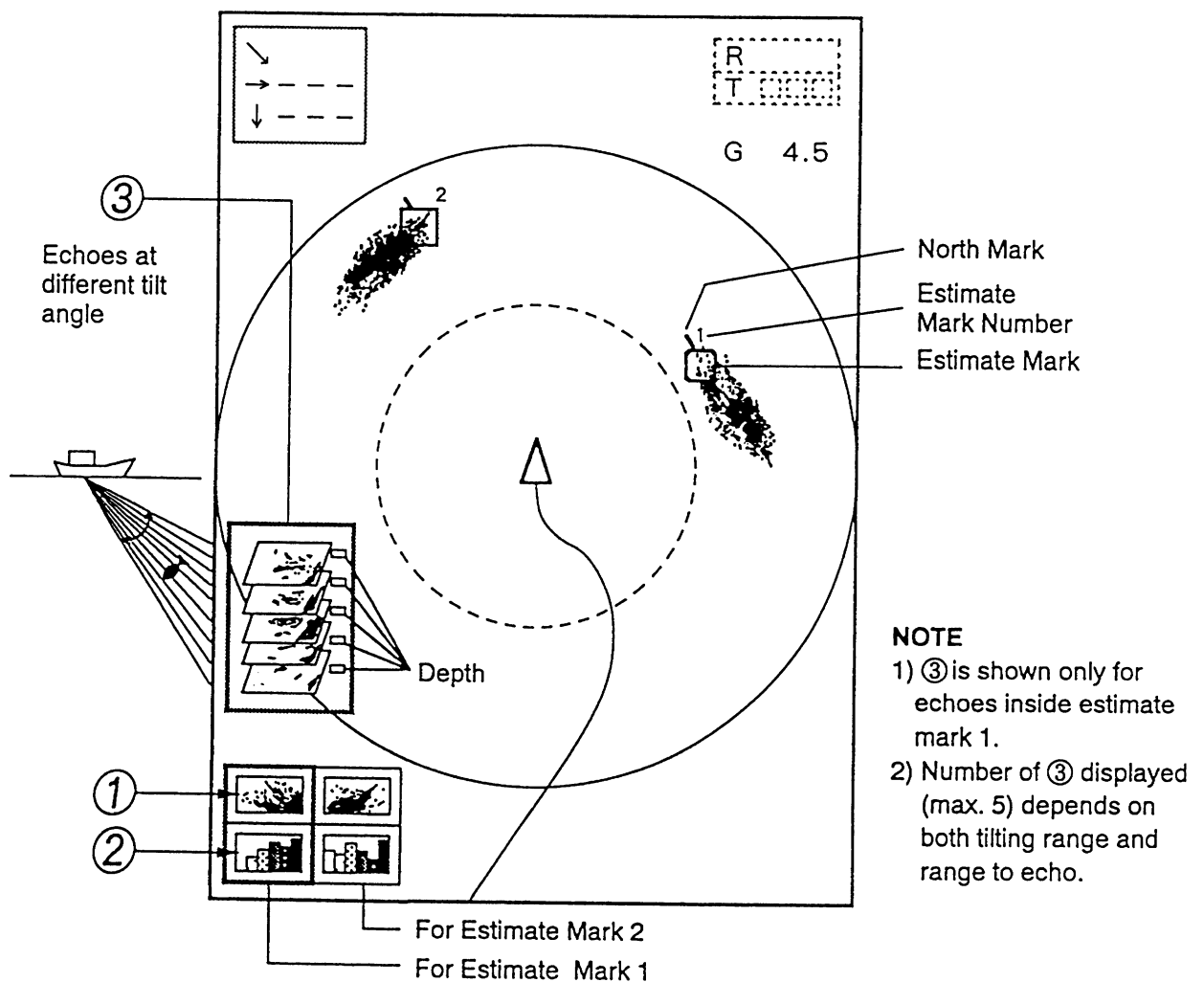


Figure 7-14 Target slice display

# PORT/STARBOARD, HORIZONTAL SLICE DISPLAYS

The port/starboard display or horizontal slice display may be displayed by pressing the HIST key. You can select which display to use on HIST DSP/GRPH in the USER menu.

## Port/Starboard Display

The port/starboard display shows echoes within the bearing (port, starboard) selected on the SYSTEM menu and displays them on the lower 1/3 of the screen. If the bearing width is set to 90°, for example, the CSH-23/24 displays echoes in both port and starboard directions. The picture is scrolled downward.

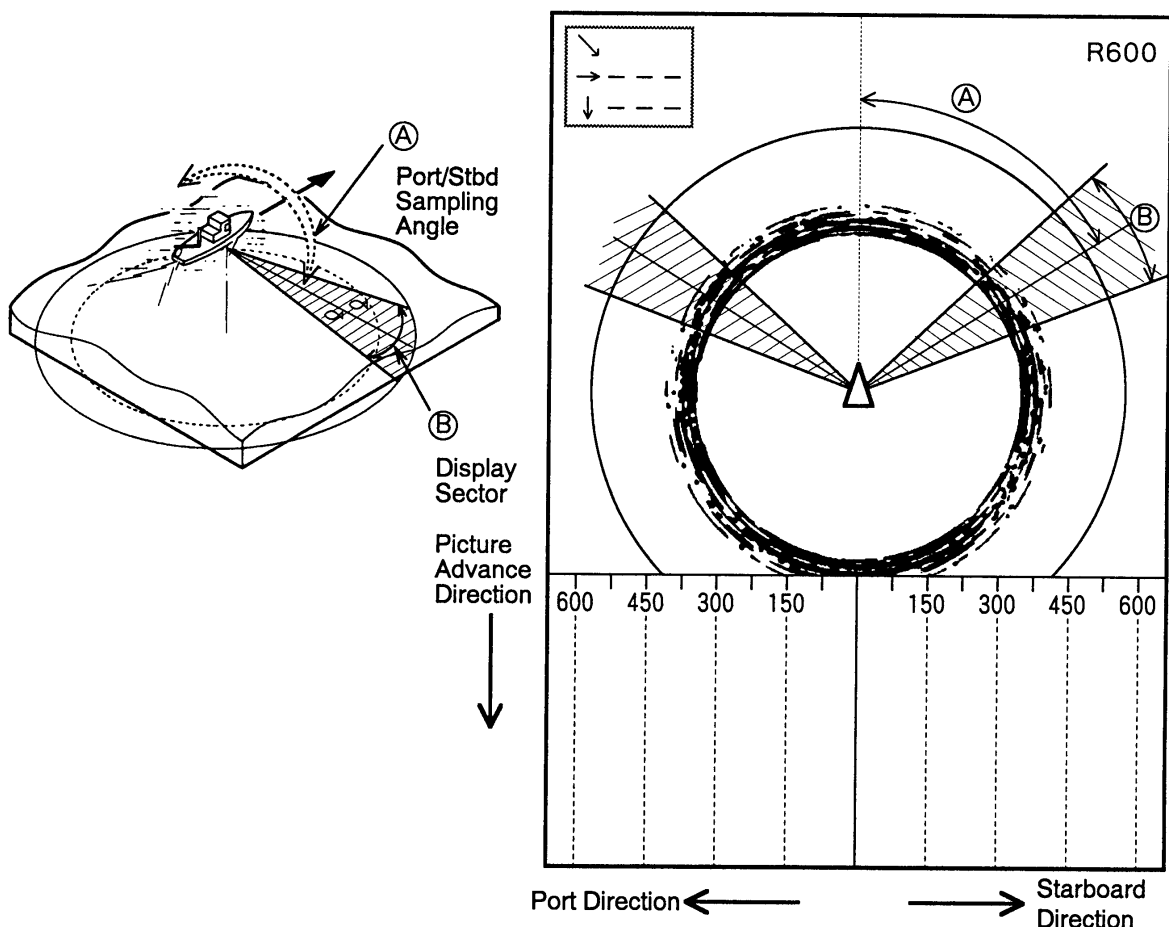
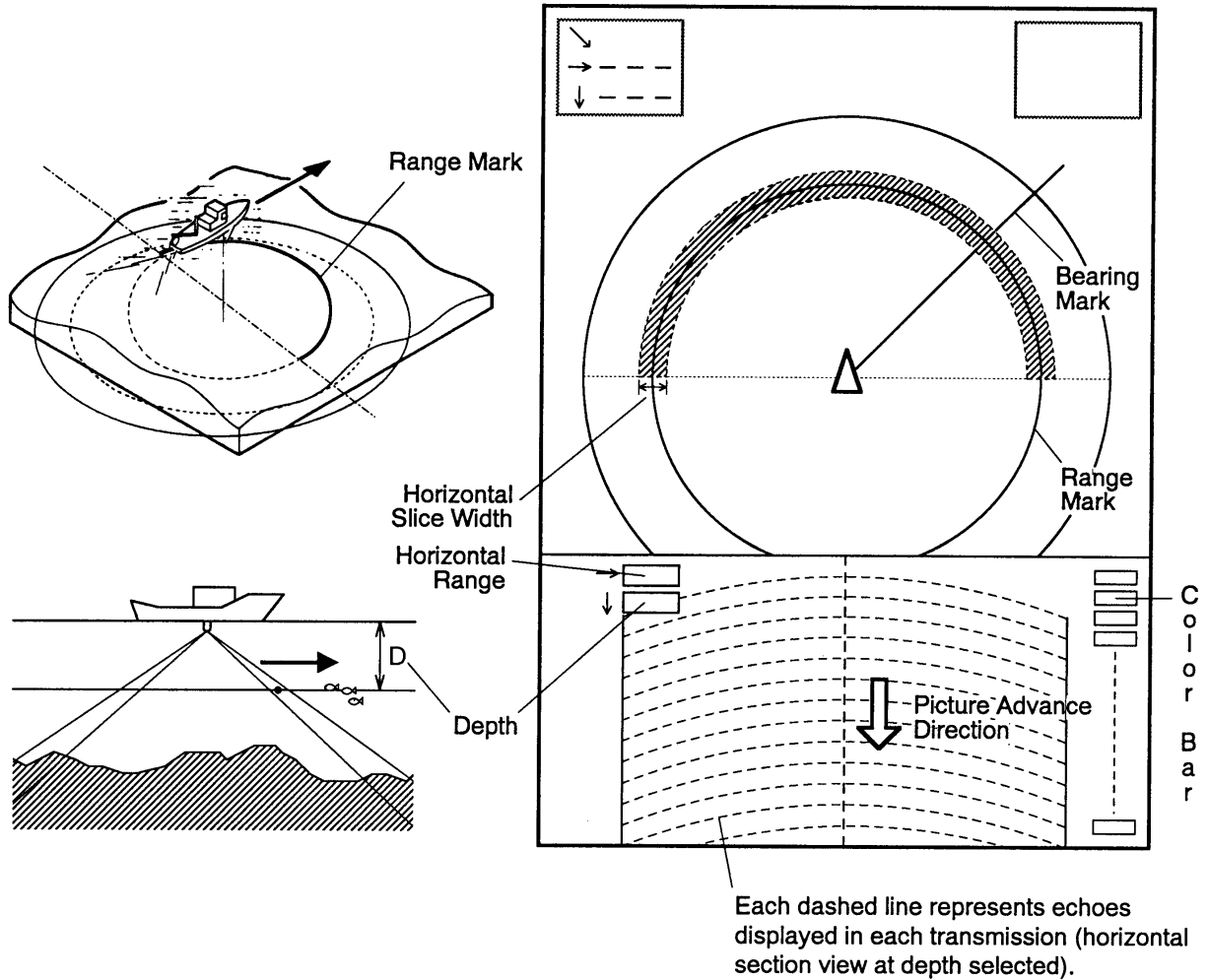


Figure 8-1 Port/starboard display

# Horizontal Slice Display

As shown in the figure below the echoes along the front half of the range mark are displayed on the lower 1/3 of the screen and scrolled downward every transmission. This feature gives you a detailed view of fish echoes at a given depth.



- **Horizontal slice sequence:**  
Place trackball mark where desired, press **R/B** key, and change tilt angle to determine slice depth.
- **Horizontal slice width setting sequence:**  
SYSTEM menu, HIST DISPLAY, H-Slice.

Figure 8-2 Horizontal slice display

# MEMORY CARD OPERATIONS

---

## Initializing Memory Cards

Before you save information to a memory card it must be initialized (formatted).

1. Press the MENU key to display the USER menu.
2. Select the CARD UTILITY menu.
3. Select Initialize. It takes more than two minutes to initialize a memory card.
4. Press the END key a few times to display the user menu.

The memory card stores 256k bytes of data. This is equivalent to about two picture screens or about 20 pictures of echoes inside the estimate mark. The following data are automatically saved as system data when the memory card is initialized: panel setting, function key settings, and menu settings.

# Saving the Picture

You can save either the whole screen or the echo inside the estimate mark to the internal memory or a memory card.

Data to Save	Saving Method	Saving to
Whole picture, marks, alphanumeric data	MEMO key and menu setting	Memory card
Echo inside estimate mark	MEMO key and menu setting	Internal memory
Net shooting data	SHOOT key	Internal memory

1. Press the MENU key to display the USER menu.
2. Select SAVE PICTURE.
3. Select item to save:
  - Whole:** Saves whole picture to memory card.
  - Est MK:** Saves echo inside the estimate mark to internal memory. (About 20 pictures can be saved.)
  - QK Save:** Saves whole screen to the internal memory. (One picture can be saved.)
4. Press the END key to close the USER menu.
5. Press the MEMO key on the main panel.

It takes about two minutes to save a whole screen to a memory card. During this time the normal picture is displayed but the unit accepts no key input.

# Transferring Echo Data from Internal Memory to Memory Card

1. Press the MENU key to display the USER menu.
2. Press arrow keys to select CARD ECHO DAT.
3. The display shows all inside-estimate mark pictures stored in the internal memory. Using the arrow keys select picture to save to memory card.
4. Press the MENU key. The lamp to the right of the memory card drive lights while picture data is being saved.
5. Press the END key several times to return to the USER menu.

# Saving Net Shooting Data

## How net shooting data is saved

The unit starts accumulating net shooting data when the SHOOT key is pressed. When net shooting is concluded by pressing the SHOOT key again, the echo inside the estimate mark and other net shooting data are saved to the internal memory. Note however that if ship's movement between pressings of the SHOOT key is less than 1/3 of the net length the unit judges that net shooting is suspended and does not save net shooting data.

## Transferring net shooting data to memory card

1. Press the MENU key.
2. Press arrow keys to select CARD NET DATA and press the MENU key.
3. If desired, according to on-screen instructions, select fish species to be added to net shooting data as a comment, and then press the MENU key.
4. If desired, enter fish quantity estimate by:
  - a) selecting number with up or down arrow key
  - b) selecting place with right or left arrow key
  - c) registering value by pressing the MENU key.

## Net shooting data contents

Net shooting data is comprised of the following:

- Echoes inside estimate mark (the ones which are displayed the first time the SHOOT key is pressed)
- Ship's position, date, time
- Ship's track, net movement, current direction, water depth and/or water temperature
- Net sonde mark

# Replaying Saved Data

## Whole picture or echo inside estimate mark

1. Press the RECALL key (on the main panel).
2. Press the right or left arrow key in sub panel 1 to select item to replay. The left arrow key selects older data (for example, data in memory card); the right arrow key newer (for example, data in internal memory).
3. After viewing picture, press the RECALL key to escape.

Note that the priority order for replay of echo inside estimate mark is internal memory-saved picture followed by memory card contents.

## Net shooting data

1. Press the NET REPLAY key (on sub panel 1).
2. At the screen bottom, comments are listed. Select the item to replay.
3. After viewing the data, press the NET REPLAY key again to escape.

# Deleting Memory Card Contents

You can delete unnecessary data from a memory card.

1. Press the MENU key to display the USER menu.
2. Select the CARD UTILITY menu and press the MENU key.
3. Select the DELETE and press the MENU key. The card contents are listed at the screen bottom.
4. Select data to delete.
5. Press the MENU key.
6. Press the END key a few times to close the menu.








# TURNING MARKS, DATA ON/OFF

You can turn marks and data on or off through the data setting window or the USER menu.

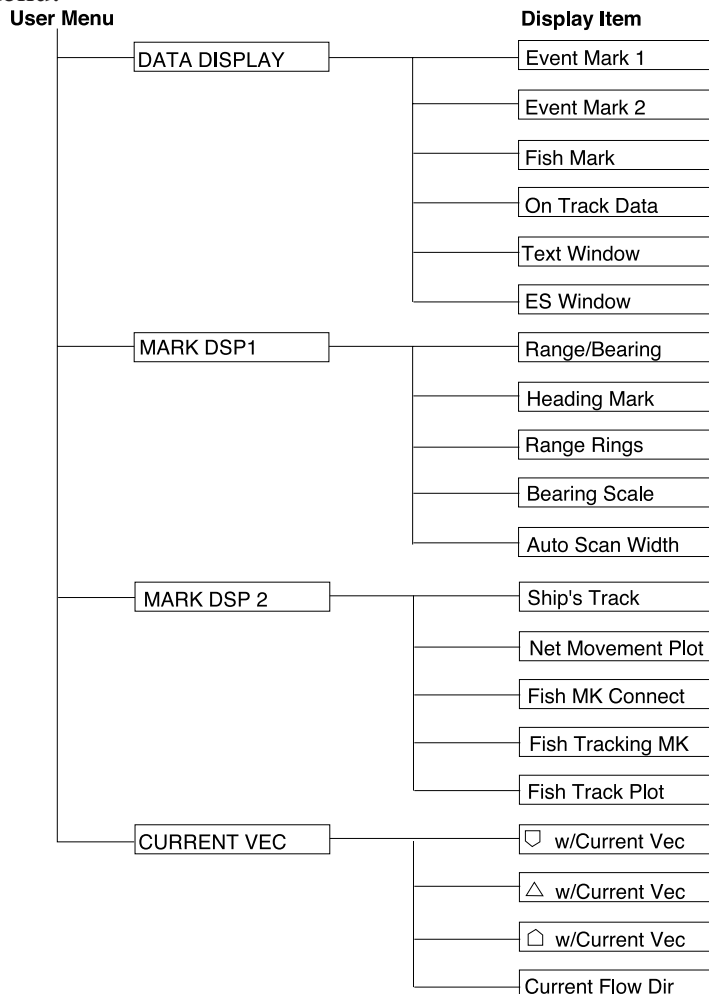
## Turning marks on/off through the data setting window

Select DELETE MK to delete the following marks:

- |               |   |   |  |
|---------------|---|---|--|
| Event Mark 1  |  | } | Each press of + or – deletes mark selected, one by one.      |
| Event Mark 2  |  |   |  |
| Fish Mark     |  |   |  |
| Own Ship Mark |  |   |  |
| Ship's Track  |  |   | Each press of + or – deletes 1/5 of overall length of track. |

## Turning marks on/off through the user menu

The following marks can be turned on/off through the USER menu:



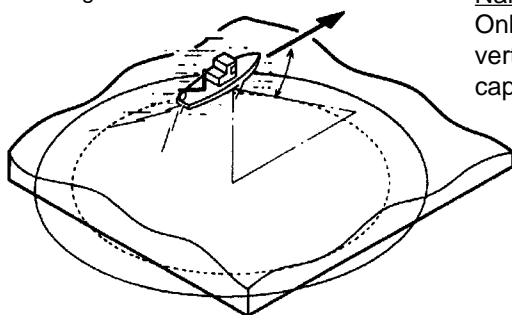
# INTERPRETING THE DISPLAY

## Seabed Echoes

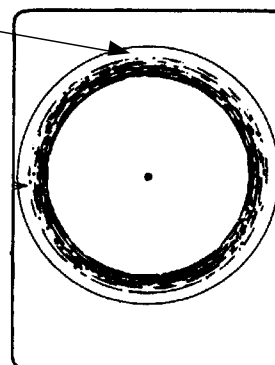
When the tilt angle is widened, the seabed echo illustrated below will appear on the display. When the tilt is narrowed, the seabed trace becomes wider and weaker. By observing the seabed condition on the display, the skipper can prevent net damage.

### (A) Flat seabed

Tilt angle: 10° to 15°

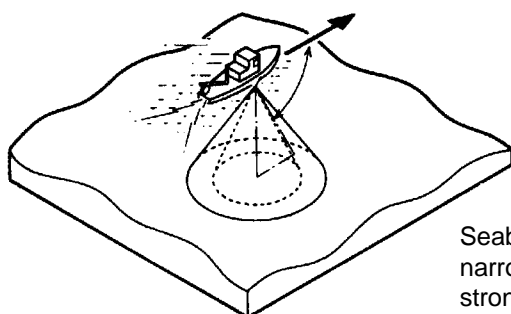


Narrow tilt angle  
Only half of vertical beam width captures the seabed.

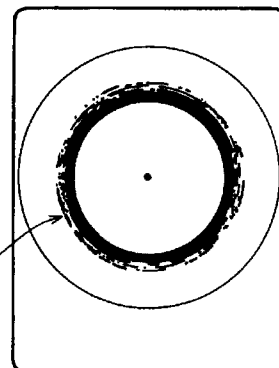


### (B) Flat seabed

Tilt angle: 20° or more

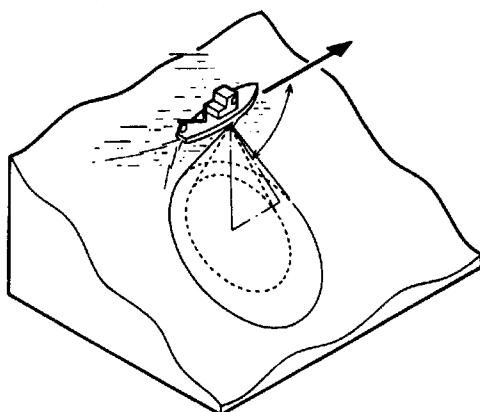


Seabed is displayed narrower and in stronger colors when compared to (A).



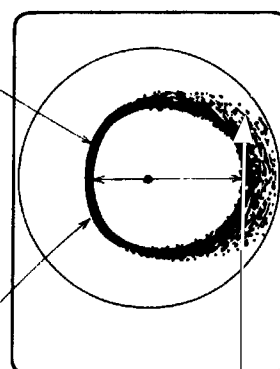
### (C) Sloping seabed

Tilt angle: 20° or more



Shallow bottom is displayed in a strong color and with a short tail.

Seabed



The deeper seabed echo is displayed in a weak color and with a long tail.

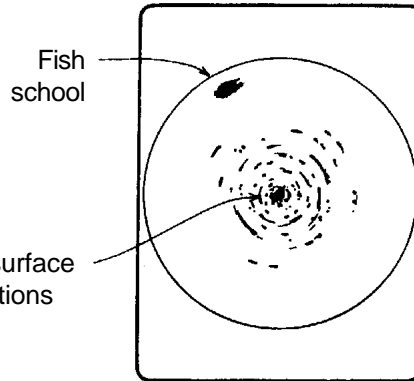
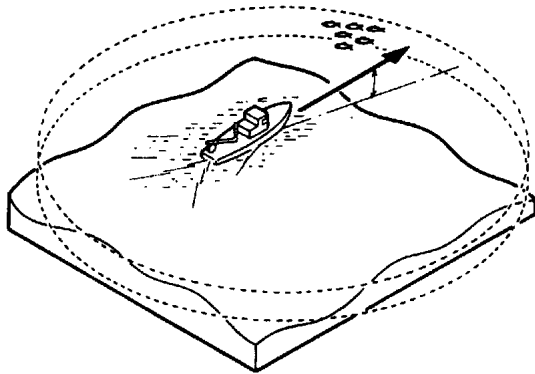
Figure 11-1 Seabed echoes

# Fish Schools

A fish school appears as a mass of echoes on the screen. The color of the mass shows the density of fish schools on the sonar beam. To find distribution and center point of a fish school, try several different tilt angles.

**(A) Sea surface fish**

Tilt angle:  $-5^{\circ}$  to  $10^{\circ}$

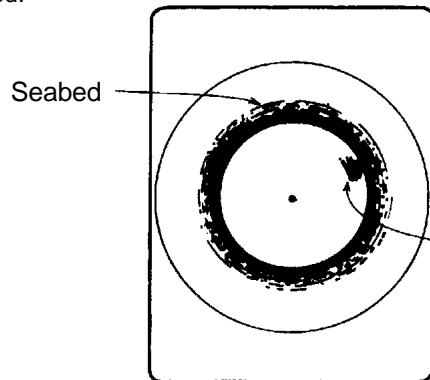
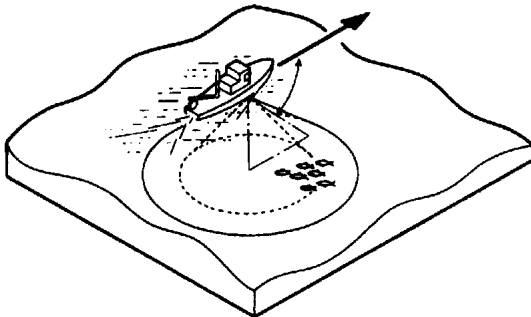


Seabed echo not displayed because of narrow tilt angle. Sea surface reflections are present.

**(B) Midwater, bottom fish**

Tilt angle:  $30^{\circ}$  or more

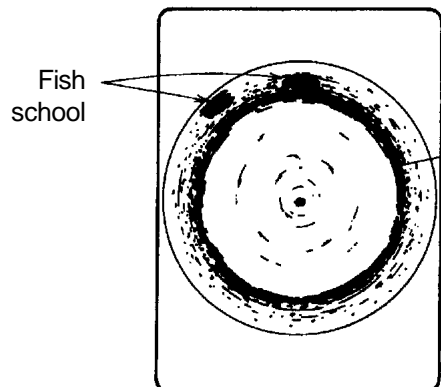
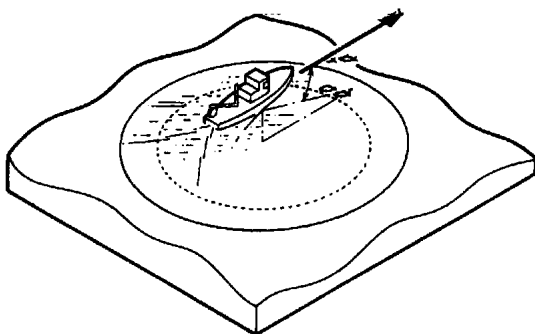
Fish echo which appears before seabed can be detected.



Fish school  
Large midwater fish school is present.

Tilt angle:  $-0^{\circ}$  to  $20^{\circ}$

Fish echo which appears together with or after seabed can be detected.



Seabed

*Figure 11-2 Fish schools*

# Sea Surface Reflections

To reduce sea surface reflections, set the tilt angle to 5° or higher, so the upper edge of the sonar beam does not hit the sea surface, or adjust TVG. When a narrow tilt angle is used, sea surface reflections cover a large area as illustrated below.

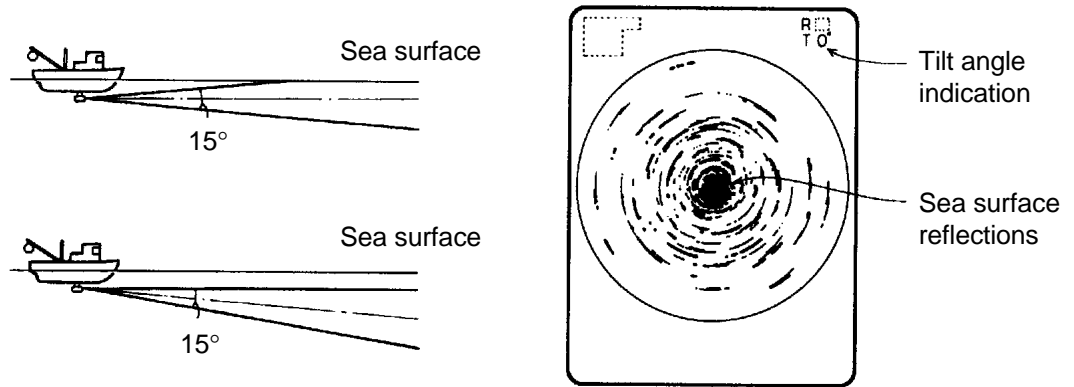


Figure 11-3 Sea surface reflections

# Wake

A wake produced by own ship or another ship can be a strong reflecting object when a narrow tilt angle is used. As the wake appears as a thick continuous line, it can be easily distinguished from a fish school. A wake contains many air bubbles which attenuate ultrasonic energy, making it difficult to sound beyond the wake.

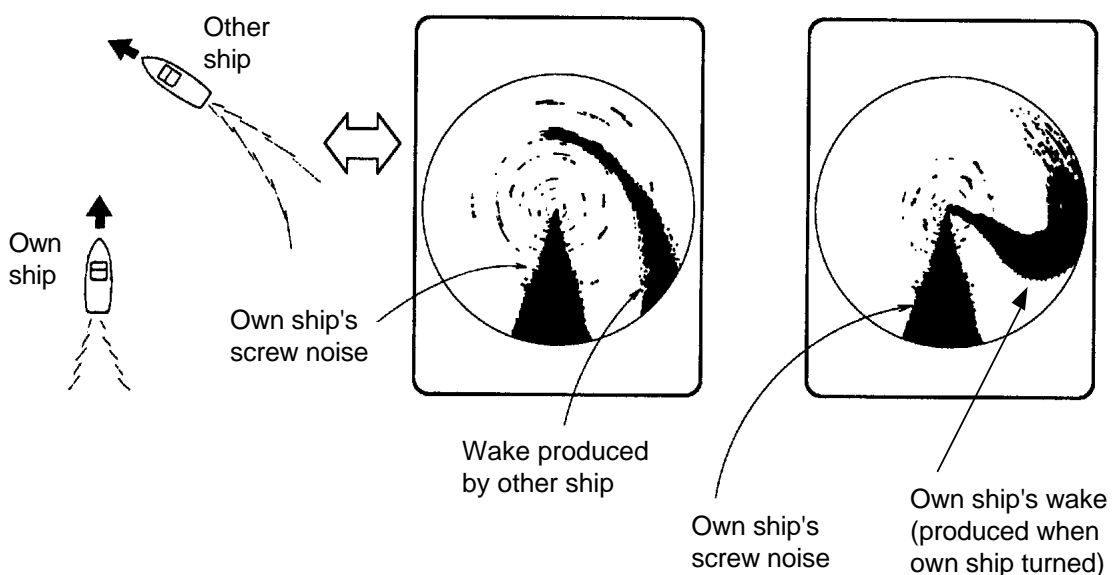


Figure 11-4 Wake appearance on the display

## False Echo by Sidelobe

An ultrasonic wave is emitted only in the direction set by the TILT lever, however there are some emissions outside the main beam. These are called sidelobes. The energy of the sidelobe is fairly weak but when the water is comparatively shallow and the bottom is rocky and hard, strong signals are detected by the sidelobe. These are represented on the display as a false echo as shown below.

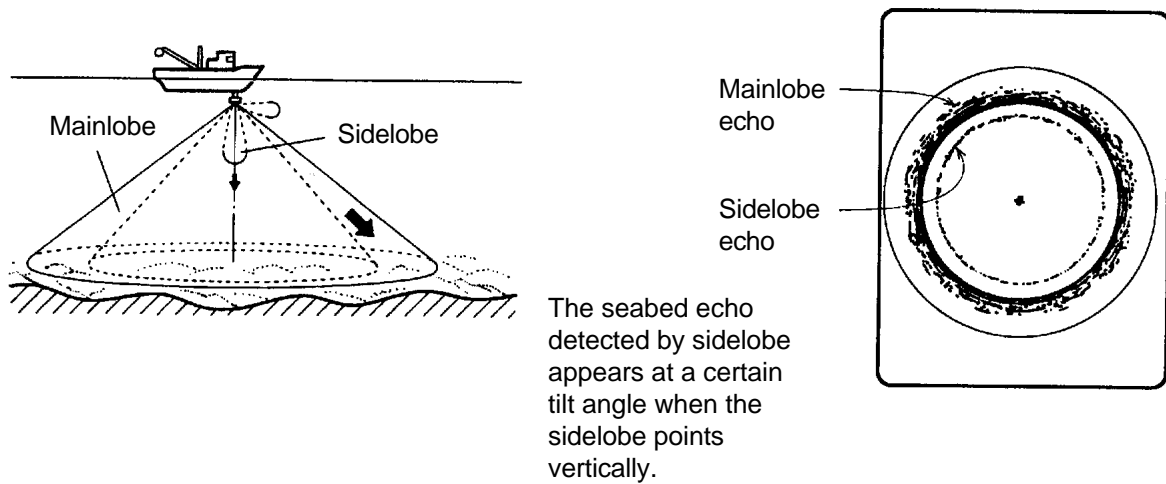


Figure 11-5 Sidelobe echoes

## Noise and Interference

Interference from a sonar on another ship appears on the screen as shown in (A) below. This interference can be suppressed by changing the CYCLE setting in TVG•TX on the data setting window. Interference from electrical equipment on board own ship appears as shown in (B) below. Noise from marine life appears on the display as shown in (C). Electrical interference and marine life noise can be suppressed with IR on the SIGNAL menu in the data setting window.

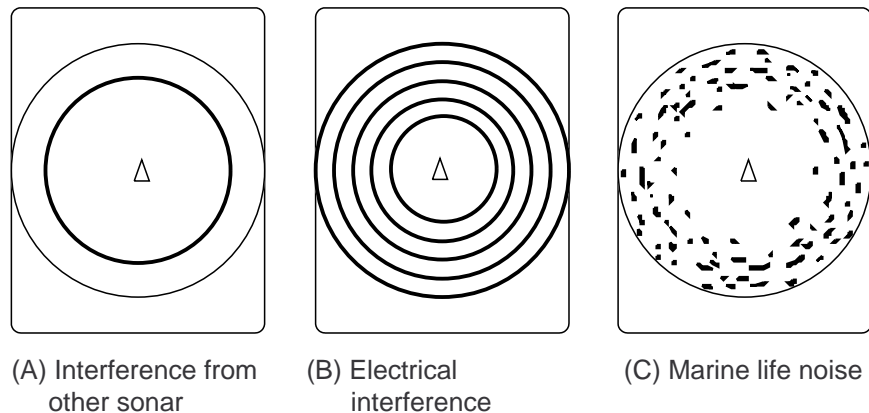


Figure 11-6 Noise and interference

# WARNINGS

---

## Overvoltage Warning

If the input voltage to this unit rises above 125 VAC, the overvoltage detection circuit activates, an alarm sounds and the message OVERVOLTAGE appears at the screen center.

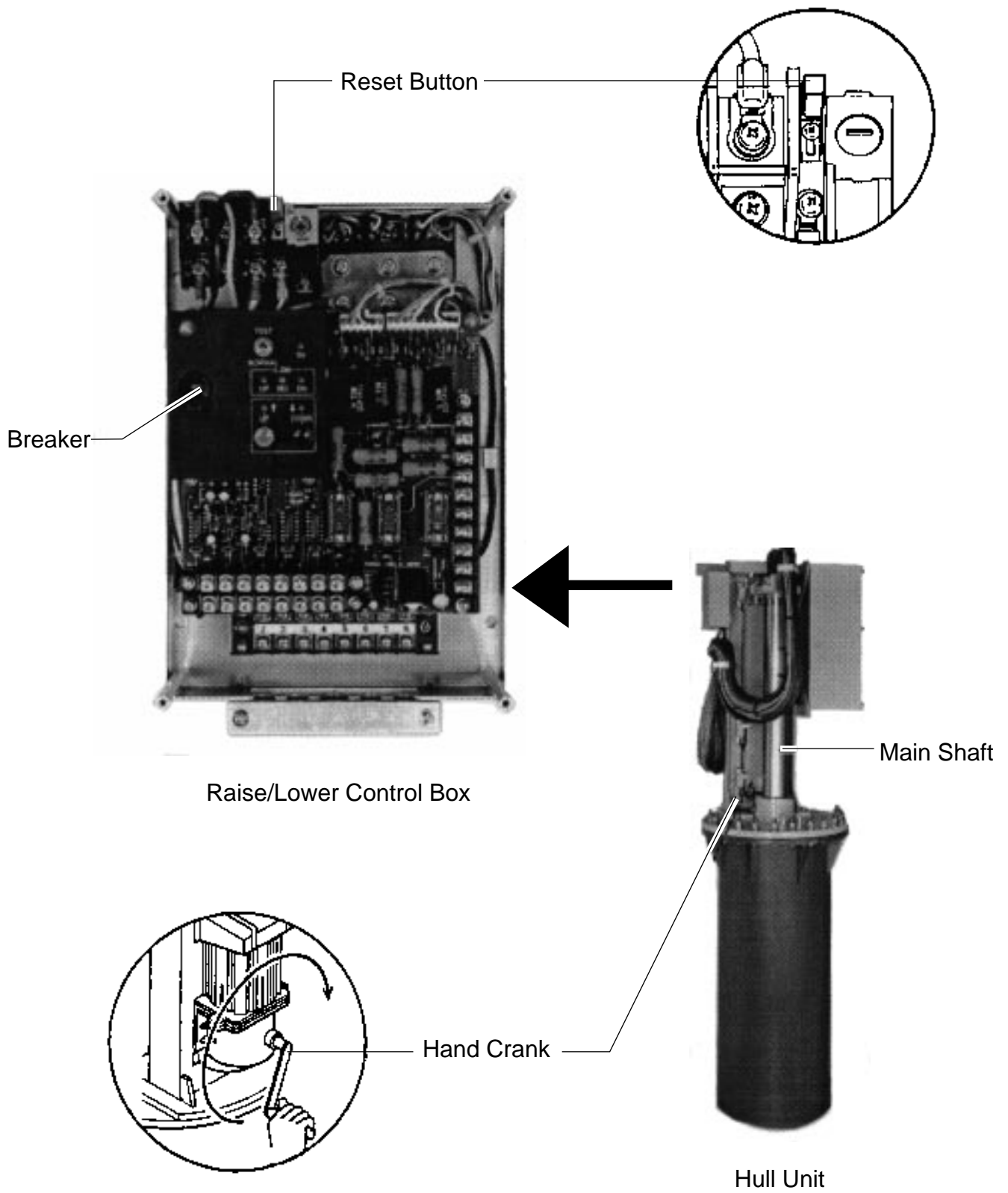
If this occurs, retract the transducer, turn the power off and check the ship's mains voltage. It should be about 100 VAC.

## Unretracted Transducer Warning

If the transducer is not completely retracted within 30 seconds after pressing **↑**, an alarm sounds and the message XDCR NOT RETRACTED! appears at the screen center.

If this occurs, do the following:

1. The power cannot be turned off because the transducer cannot be retracted. Turn off the main breaker for the display and power supply units to stop operation.
2. Confirm that the net is not tangled in the transducer.
3. Confirm that the breaker inside the raise/lower control box (mounted on the hull unit) is on.
4. Remove the cover of the raise/lower control box. Push the (Red) reset button to reset the raise/lower control box.
5. Turn on the power and press **↑** to retract the transducer into the tank. If it does not retract, the main shaft of the hull unit may be bent. Turn off the power and manually raise the transducer up to the highest position by using the hand crank. (See the illustration on the next page.)



*Figure 12-1 How to manually raise the transducer*

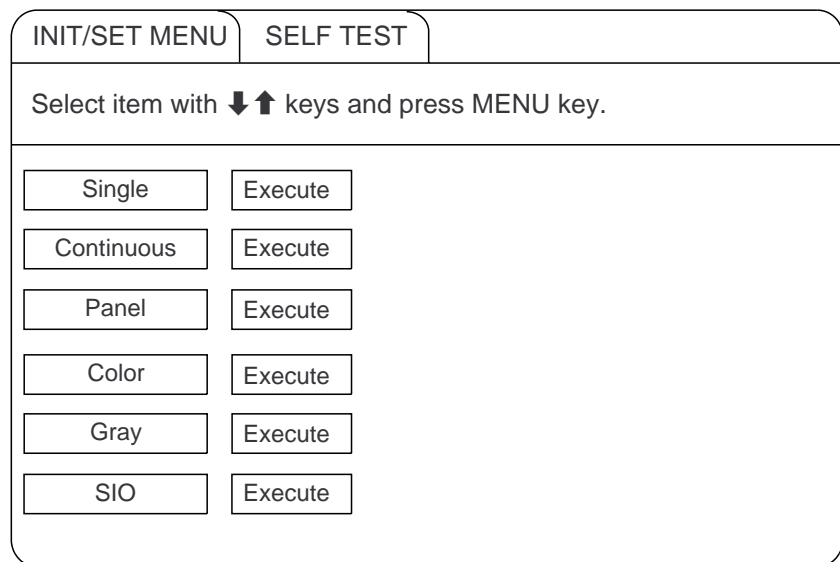
# SELF TESTS

The CSH-23/24 has various self tests to check it for proper operation. If a test reveals equipment malfunction do not attempt to check inside the equipment. There are no user serviceable parts inside the equipment.



## Opening the Self Test Menu

1. Turn on the power while pressing and holding down the MENU key.
2. Press arrow keys to select SELF TEST.



*Figure 13-1 SELF test menu*

3. Press up or down arrow key to select test desired.
4. Press the MENU key to start test.



# Self Test Description

## Single test

The ROM, RAM and other devices of the display unit are checked once. Control is returned to the SELF TEST menu when the test is completed.

START UP TEST			
DCON	105-0574-2xx ROM = OK RAM = OK DPRAM = OK P.W = OK	105-0351-1xx	
DRAW	105-0575-2xx ROM = OK RAM = OK	105-0576-1xx	
DUAL	105-0381-2xx ROM = OK RAM = OK	105-0381-1xx	
ES	105-0382-1xx ROM = OK RAM = OK		
SLICE	105-0353-1xx ROM = OK RAM = OK		
PSIO	105-0352-1xx ROM = OK RAM = OK		
PIF	105-0415-1xx ROM = OK RAM = OK		
-----			
RX1 1X1	105-0226-1xx	ROM = OK RAM = OK	RAM = OK RAM = OK
RX2 1X2		ROM = OK RAM = OK	RAM = OK RAM = OK

**Note:** Above program numbers are for CSH-23.

*Figure 13-2 Single test*

## Continuous test

The devices of the display unit are checked continuously.

CONTI TEST		
DCON	ROM = OK RAM = OK DROM = OK DPRAM = OK P.W = OK EEPROM = OK REACT = OK	
DRAW	ROM = OK RAM = OK VRAM = OK DPRAM = OK CLT = OK	
DUAL	ROM = OK RAM = OK DPRAM = OK	
ES	ROM = OK RAM = OK DPRAM = OK	
SLICE	ROM = OK RAM = OK DPRAM = OK	
PSIO	ROM = OK RAM = OK	
PIF	ROM = OK RAM = OK MEMCARD = OK	

*Figure 13-3 Continuous test*

## Panel test

This test checks the keys of the main and sub panels and the remote control box. Press and release each key. Its on-screen location should display “1” when the key is pressed and “0” when released. To escape from the test reset the power.

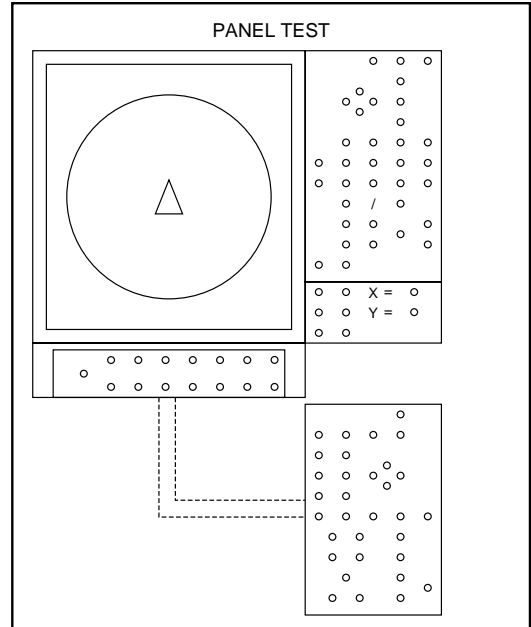


Figure 13-4 Panel test

## Color test

This test checks for proper display color. To escape from the test reset the power.

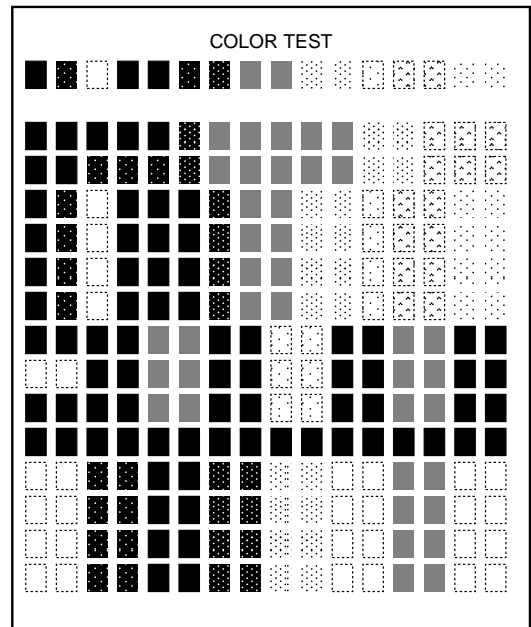
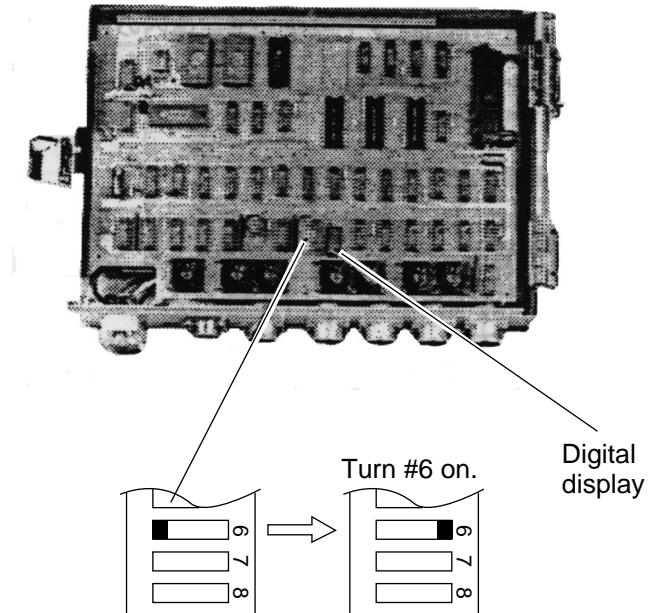


Figure 13-5 Color test



# Interface Unit CS-120A Self Test

1. Open the cover of the interface unit.
2. Find DIP switch DP-1 on the lone circuit board. Turn switch #6 on to start the self test. The results of the check appear on the digital display beside the DIP switch.
3. Turn the DIP switch off after completion of the test.



If the readout shows "0" the unit is functioning properly. If it is not working properly any of the following nine numerals or six alphabets appear.

1, 2, 3, 4, 5, 6, 7, 8, 9, A,  
b, c, d, E, F, :

*Figure 13-8 Interface unit CS-120A, cover opened*

# INPUT DATA SELECTION

## Selection of Data at Interface Unit CS-120A

Nav data and fish data input from external equipment can be turned on or off at DIP switch DP-1 in the Interface Unit CS-120A.

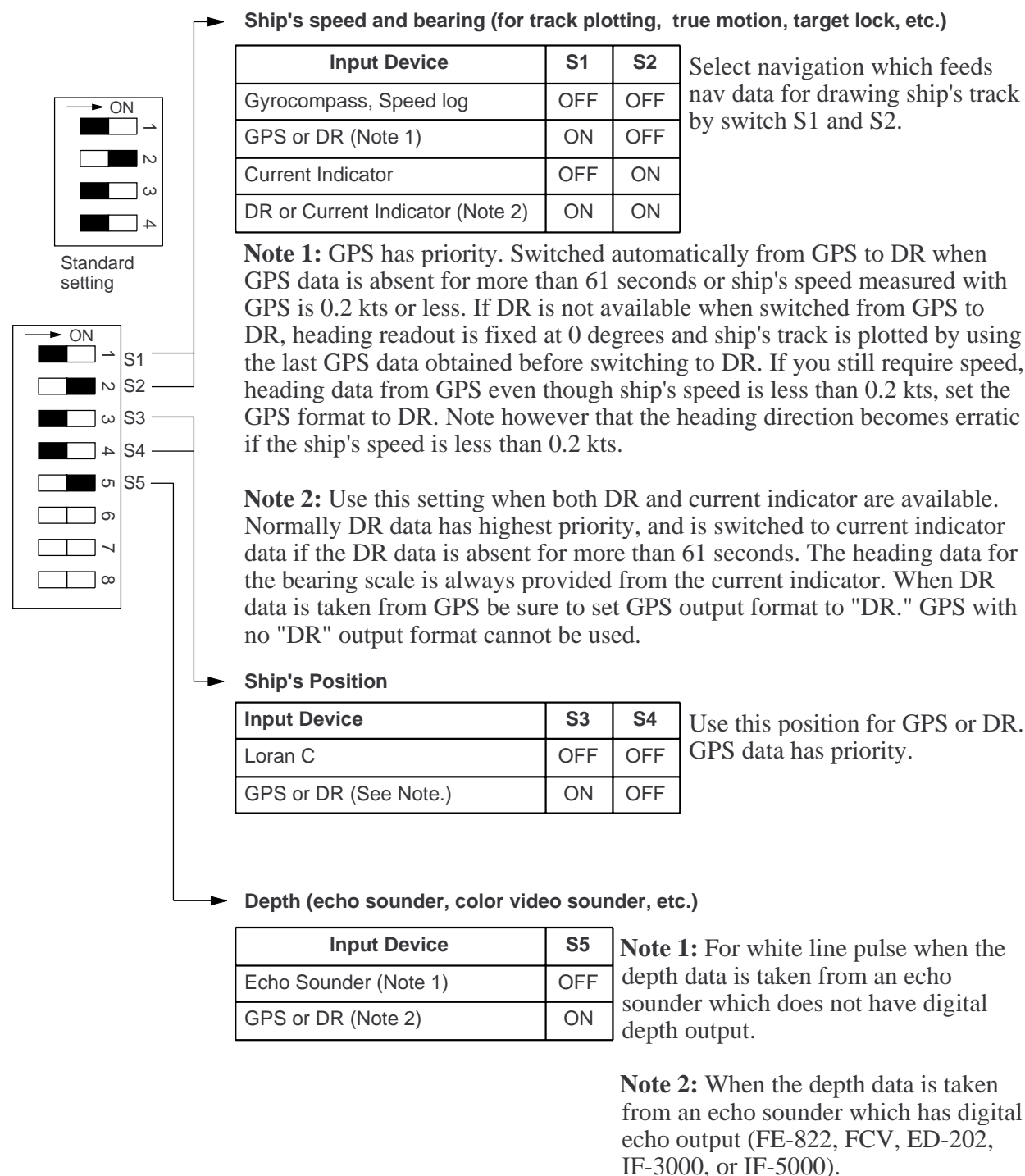
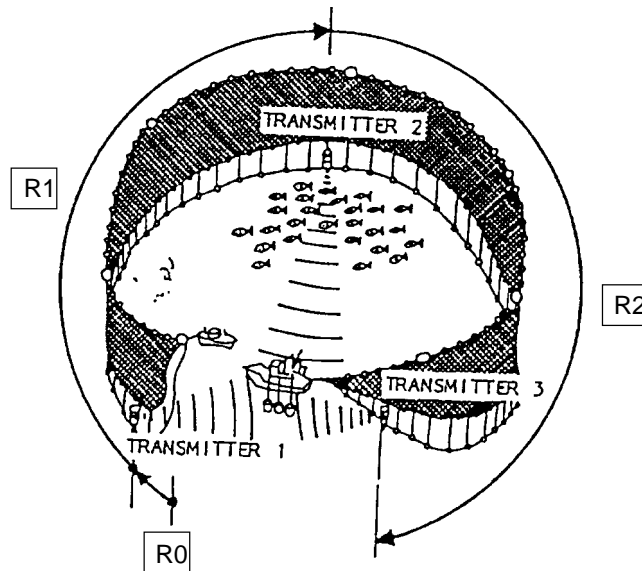


Figure 14-1 DIP switch settings in the interface unit

# Setting Distances Between Net Sonde Transmitters

To accurately display the net shooting mark and net sonde mark position, the distance between transmitters must be correctly set. This is done on the DATA SET menu.



- R0: Length of net from its end to transmitter1 in meters.
- R1: Length of net between transmitters 1 and 2 in meters.
- R2: Length of net between transmitters 2 and 3 in meters.

Figure 14-2 How to measure distances between transmitters

## How to set net sonde transmitter distances

1. Press the MENU key while pressing and holding down  $\diamond$ . The DATA SET menu appears.

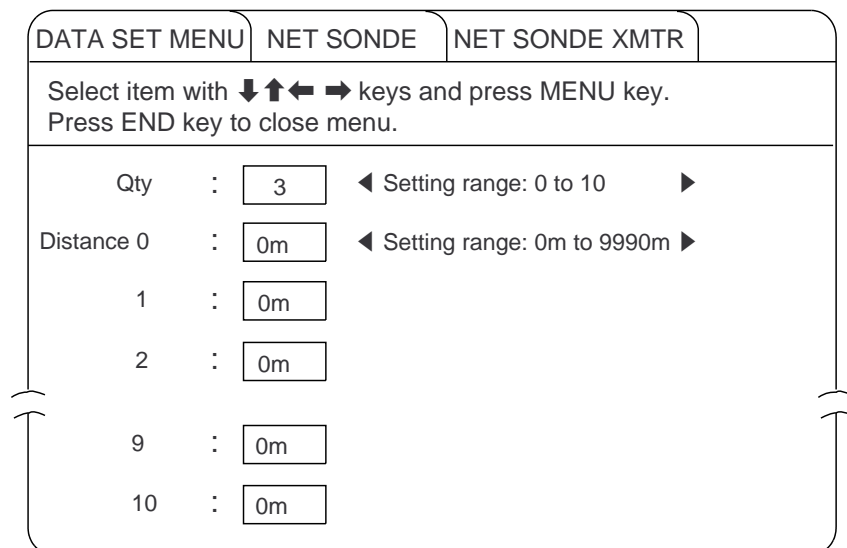


Figure 14-3 DATA SET menu

2. Select NET SONDE and then “Net Sonde XMTR”.
3. Enter number of net sonde transmitters and distances between them.

# MAINTENANCE

**⚠ WARNING**

**Do not open the cover.**

There are no user-serviceable parts inside. Refer any repair work to a qualified technician.



## Display Unit Maintenance

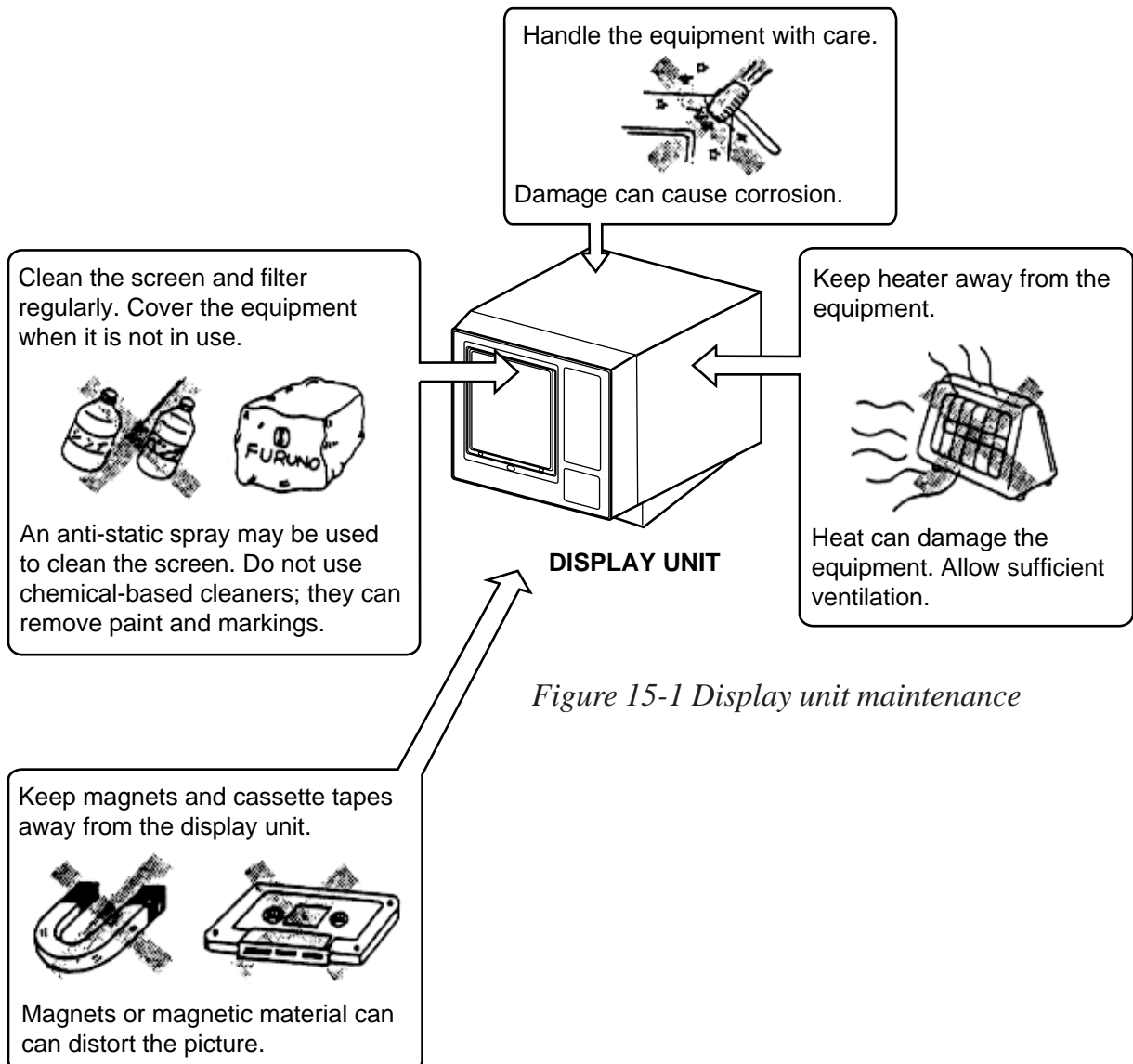


Figure 15-1 Display unit maintenance

# Hull Unit Maintenance

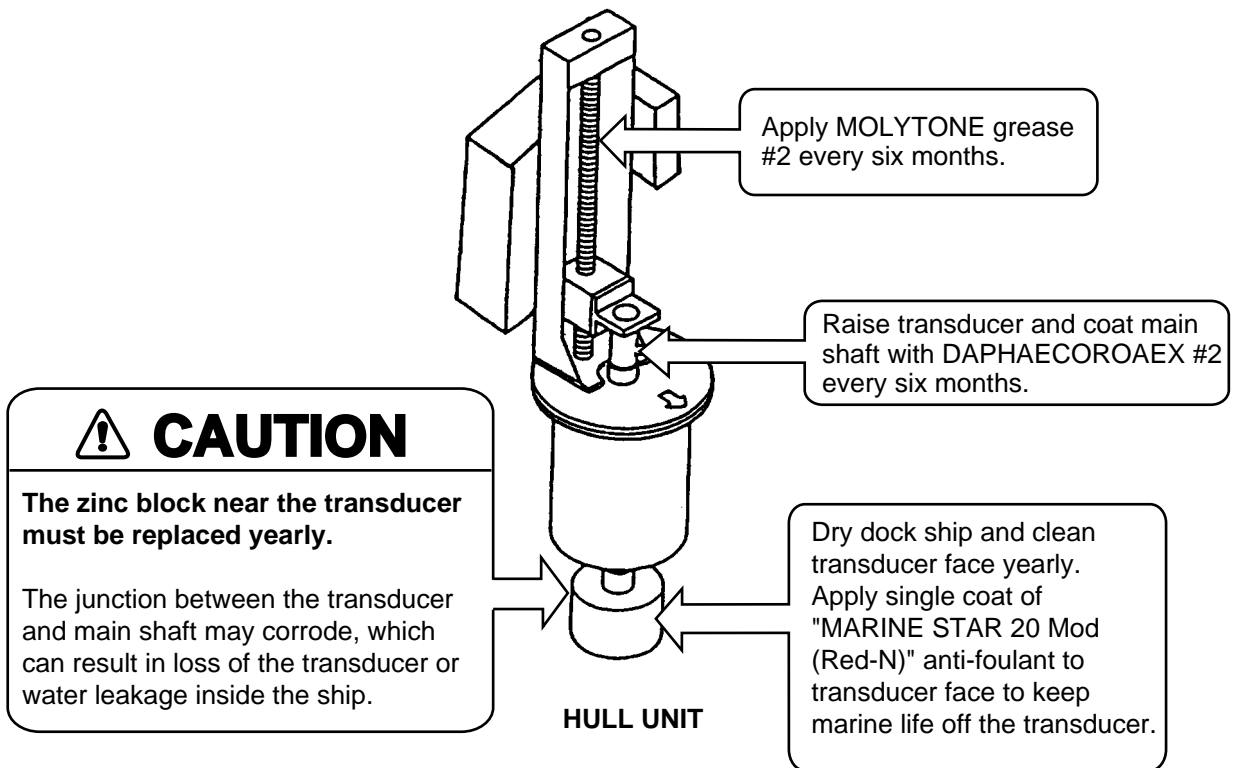
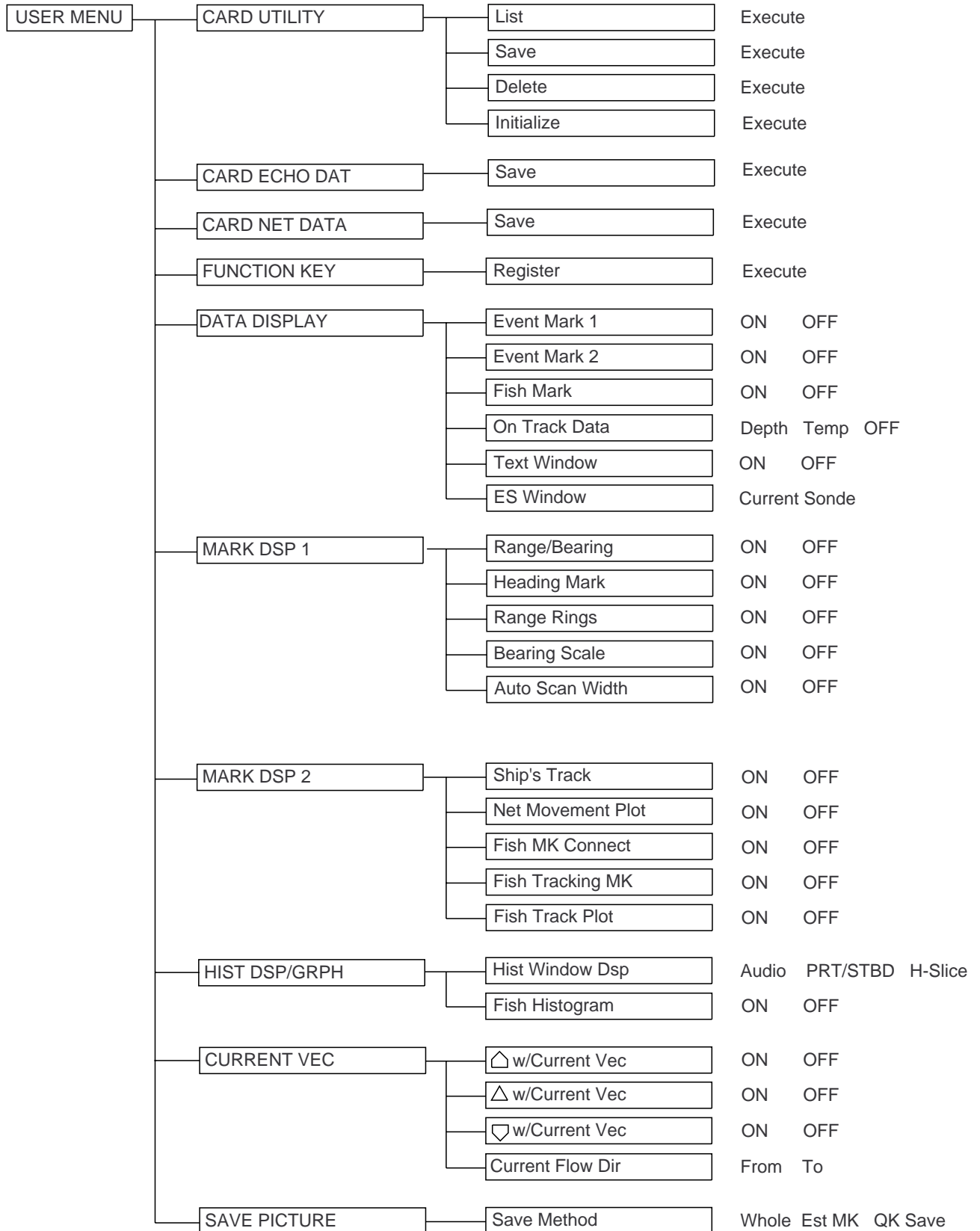


Figure 15-2 Hull unit maintenance

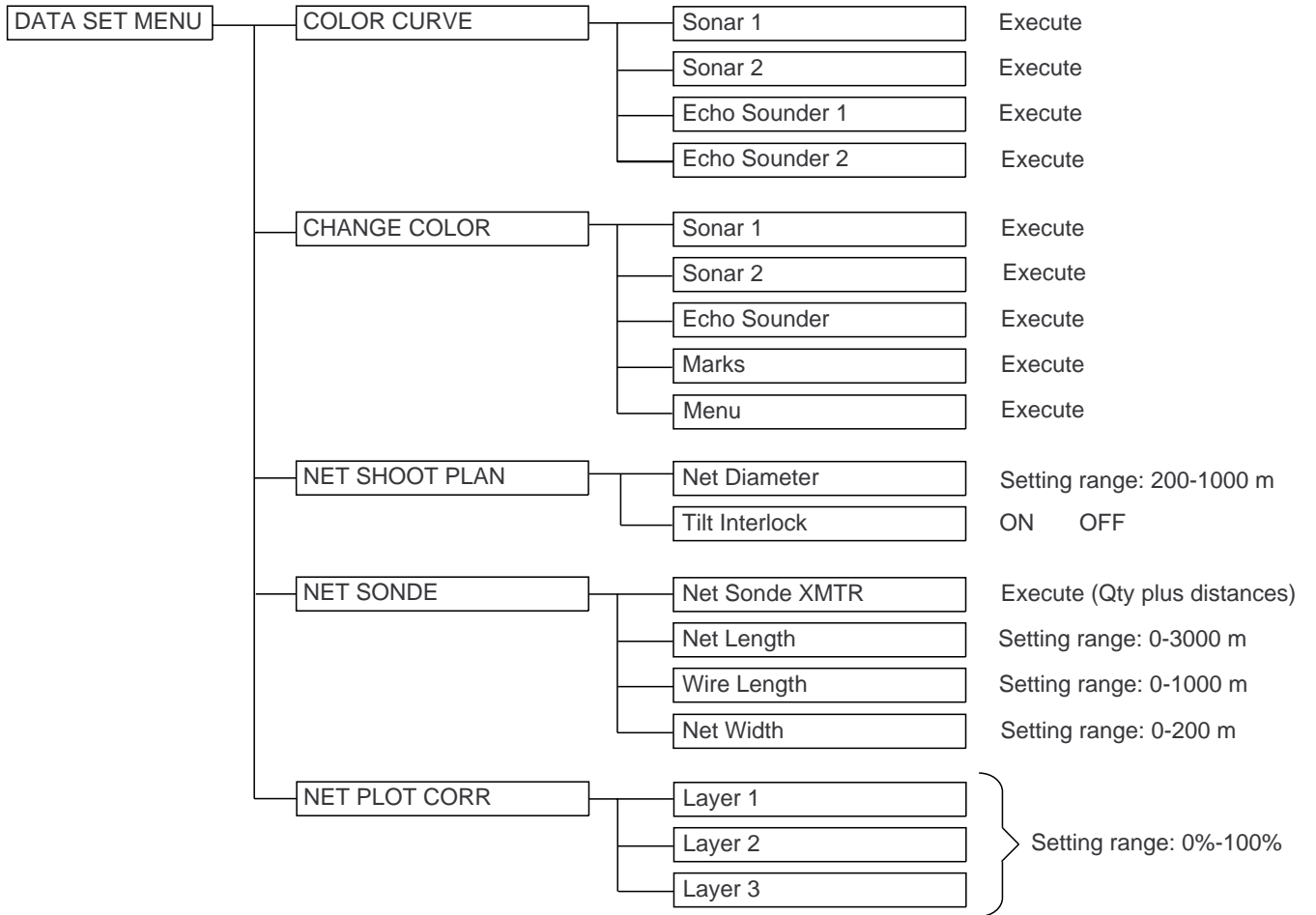


# MENU TREE

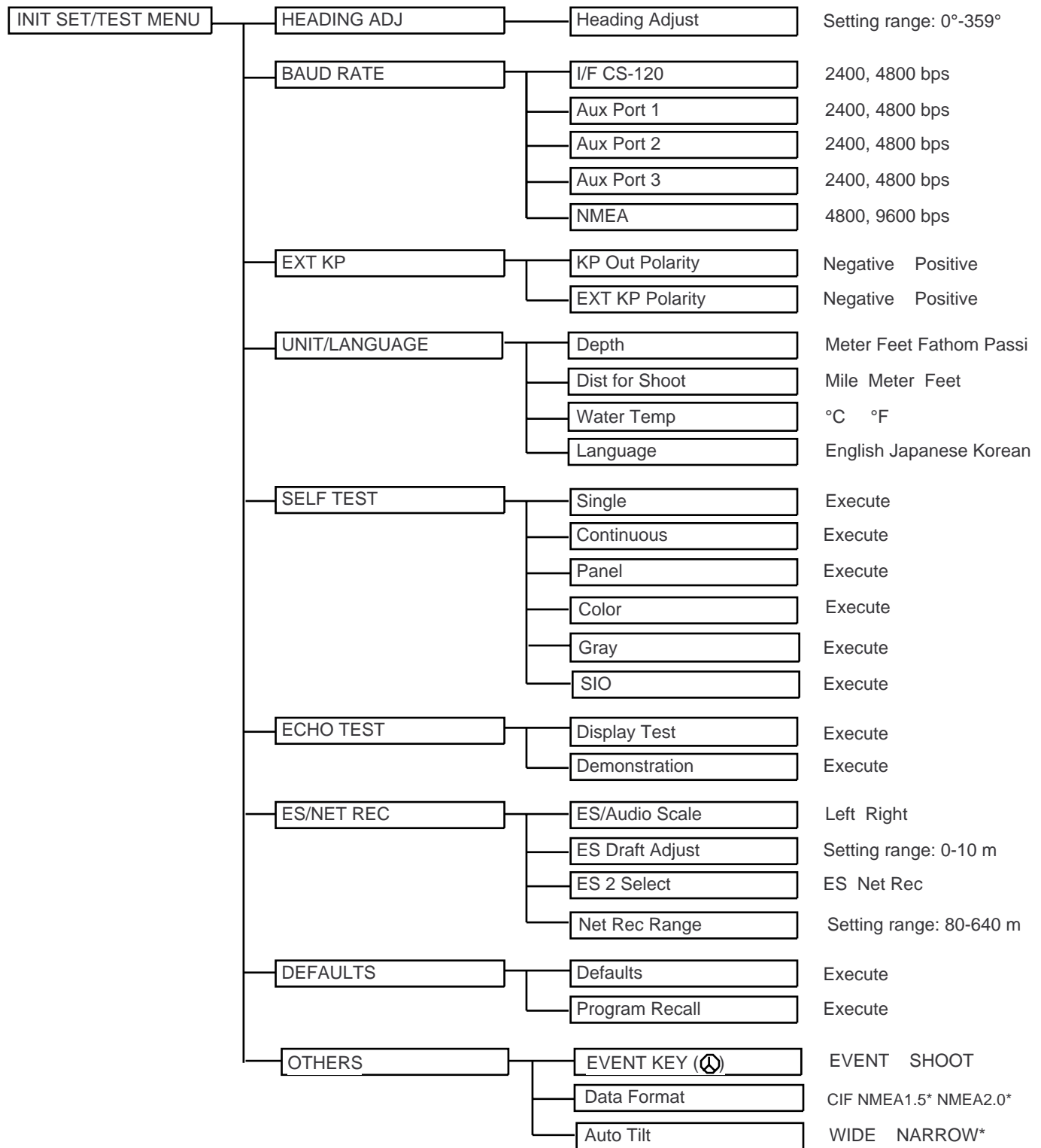
## USER Menu



# DATA SET Menu

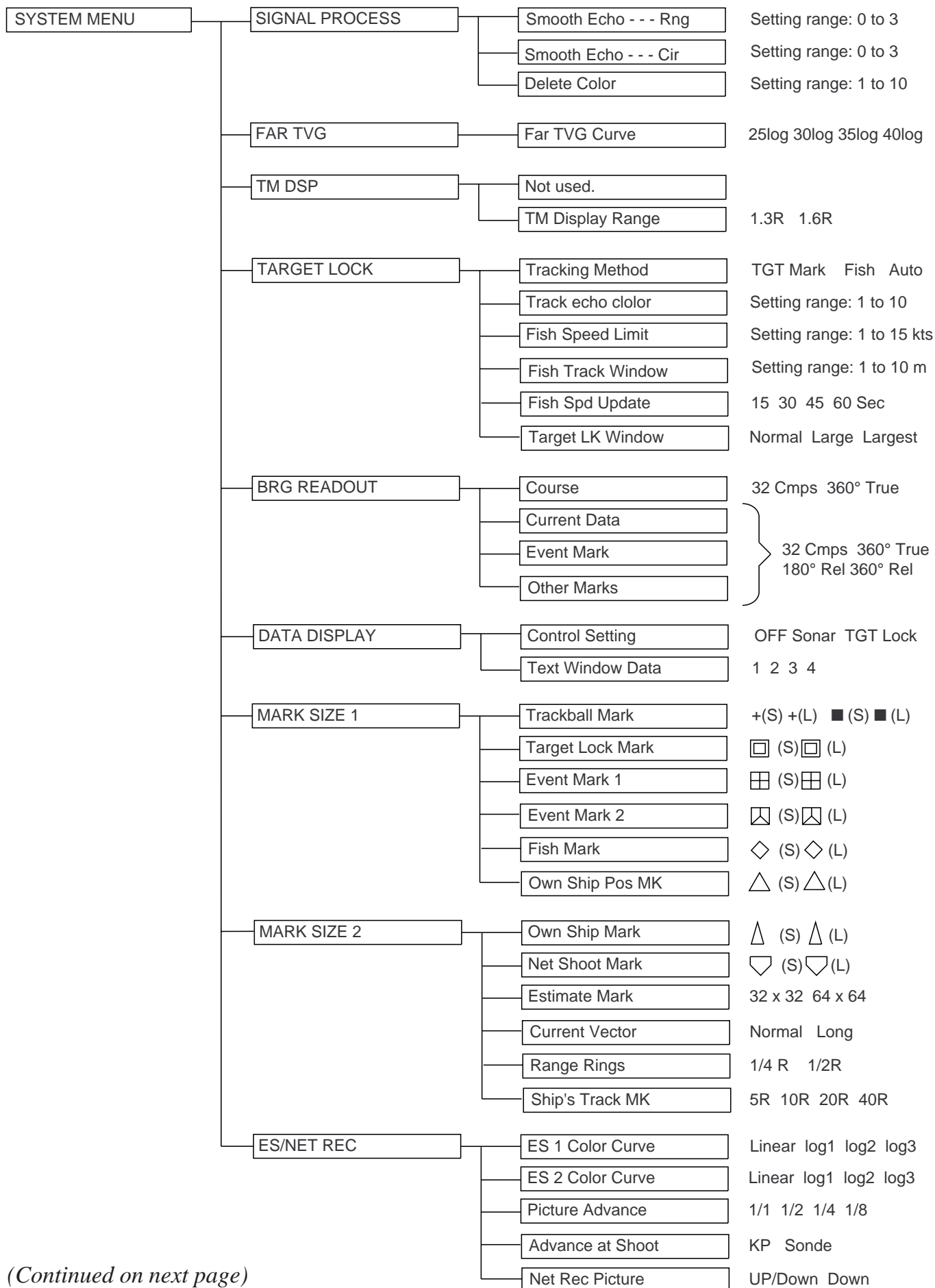


# INIT SET/TEST Menu



\*: Under development

# SYSTEM Menu



(Continued on next page)

SYSTEM MENU

*(Continued from previous page)*

HIST DISPLAY

H-Slice Width

1 2 3 4

PRT/STBD Sample

Setting range: 0°-180°

INTERLOCK

Tilt

ON OFF

Range

ON OFF

Event Mark

ON OFF

Fish Mark

ON OFF

Net Shoot Mark

ON OFF

Target Lock

ON OFF

DEFAULTS

Defaults

Execute

# SPECIFICATIONS

Model: CSH-23/24- 1 (Freq.: 24 kHz) 4 (Freq: 40LkHz)  
 2 (Freq.: 28 kHz) 5 (Freq: 40HkHz)  
 3 (Freq.: 32 kHz) 6 (Freq: 45 kHz)

## 1. GENERAL

### (1) Range, TX Cycle, Pulselength

Basic Range	Range (m)		TX Cycle (sec)	Pulselength (msec)
	Off center "OFF"	Off center "ON"		
60	0 - 60	0 - 80	0.09 - 0.32	0.5 - 1.5
100	0 - 100	0 - 133	0.14 - 0.39	0.5 - 2
150	0 - 150	0 - 240	0.21 - 0.53	0.5 - 3
200	0 - 200	0 - 320	0.28 - 0.64	0.5 - 4
300	0 - 300	0 - 480	0.41 - 0.85	0.6 - 6
400	0 - 400	0 - 640	0.54 - 1.06	0.8 - 8
500	0 - 500	0 - 800	0.68 - 1.28	1.0 - 10
600	0 - 600	0 - 960	0.81 - 1.49	1.2 - 12
800	0 - 800	0 - 1280	1.08 - 1.92	1.5 - 15
1000	0 - 1000	0 - 1600	1.34 - 2.34	2.0 - 20
1200	0 - 1200	0 - 1920	1.61 - 2.77	2.5 - 25
1600	0 - 1600	0 - 2560	2.14 - 3.62	3.0 - 30
2000	0 - 2000	0 - 3200	2.68 - 4.48	4.0 - 40

### NOTE

- 1) Transmission cycle is selectable in 10 steps.
- 2) External keying pulse can be used as a trigger.
- 3) Maximum range scale does not mean maximum range.  
 Detection capability depends on nature of fish school and sea condition.

### (2) Audio Search

Sector 30°, 60°, 90°, 180°, 330°, selectable  
 Method By built-in loudspeaker  
 Output 2 W  
 Frequency 1.1 kHz with reverberation effect

### (3) Transceiver

Transmitter	High power MOS FET amplifier with 10-step power reduction switch
Receiver	Low noise superheterodyne, continuously scanning beam forming, TVG, AGC, signal/processing, interference rejecter, horizontal vertical beam switching.

### (4) Beamwidth (-3 dB) and Tilt Angle

TX Beamwidth	360° (horizontal) x 10° to 13° (Vertical)
RX Beamwidth	8° to 16° (horizontal) x 11° to 14° (Vertical)
Tilt Angle	-5° (upward) to 60° (downward), continuous. <b>NOTE:</b> Beamwidth depends on transmitter frequency.

## 2. DISPLAY

- (1) Picture Display CSH-23: PPI display on 15 inch non-glare, high-resolution color CRT  
CSH-24: PPI display on 21 inch non-glare, high-resolution color CRT
- (2) Color 16 colors (sonar picture), 4 colors (marks)
- (3) Display Mode
- Normal Mode (\*with or without data display)
  - Off-center
  - Echo sounder combination (normal plus echo sounder)
  - Audio combination
  - Port/ starboard combination
  - Horizontal slice combination
  - Target slice
  - True motion\*
- (4) Display Marks Own ship mark, heading mark, range rings, range/bearing mark, trackball mark, event mark, net shooting mark, fish mark, estimate, mark, bearing scale, north mark\*, ship's track\*, current mark\*, net sonde mark\*, target lock mark\*
- (5) Alphanumeric Data Sonar picture (range, tilt angle, gain) Trackball mark data (slant range, horizontal range, depth, bearing), Event mark data (horizontal range, depth, first event marked depth, bearing), Fish mark data (distance moved\*, direction\* and speed\* between two latest fish marks), Estimate mark data (estimation of fish volume by echo strength), Net shooting data (time and distance run\* between turning on and off of net shooting mark), Setting change data (new setting appears in larger characters for 5 seconds when changed), Current data \*(current speed, direction, layer, depth), Navigation data \*(ship's speed, heading, water depth, water temperature), Own ship's position \*(latitude/longitude), Net sonde data \*(net depth, distance to seabed, water temperature, sinking speed of net)

(6) Features

Custom mode, interference rejector, afterglow, noise limiter, delete color, memory card (save and recall of picture, echo inside estimate mark and net shooting data), automatic tilt, automatic target tracking \*(target lock), external KP sync, heading up, north up\*, fish alarm, overvoltage warning, unretracted transducer warning, remote control

\*: External sensor required.

### 3. HULL UNIT

	800 mm Travel	1200 mm Travel	1600 mm Travel
XDCR Travel	600 mm/800 mm	800 mm/1200 mm	1600 mm/1200 mm
Raising Time	16 sec (for 800mm travel)	22 sec (for 1200 mm travel)	28 sec (for 1600 mm travel)
Lowering Time	15 sec (for 800mm travel)	20 sec (for 1200 mm travel)	25 sec (for 1600 mm travel)
Driving System	Remote electric control		
Allowable ship's speed	18 knots (15 knots during raise/lower operation)		15 knots (12 knots during raise/lower operation)

### 4. POWER CONSUMPTION

100VAC,50/60Hz, 1f, 1kVA on average, 3kVA max. 110/220VAC operation available with stepdown transformer PT-400.

### 5. ENVIRONMENTAL CONDITION

(1) Temperature 0°C to 50°C

(2) Relative Humidity 95% or less

### 6. COATING COLOR

(1) Display Unit N3.0 Newton No.5 for front panel  
Munsell 2.5GY 5/1.5 for cabinet

(2) Transceiver Unit and Hull Unit

Munsell 2.5G 7/2 Newton No.5



# INDEX

## A

- AGC ..... 3-3
- 2AGC ..... 3-3
- AUDIO ..... 7-5

## B

- Beamwidth ..... 3-6

## C

- Color Bar ..... 4-7

## D

- DATA SET Menu ..... 5-8
- Data Setting Window ..... 1-5
- Display Mode ..... 2-2

## E

- Echo Sounder Combination Display ..... 4-2
- Eliminating Unwanted Feeble Echoes ..... 3-1
- Estimate Mark ..... 4-6
- Event Mark ..... 7-10

## F

- False Echo ..... 11-4
- Fish Alarm ..... 7-6
- Fish Mark ..... 4-5
- Fish Movement ..... 4-5
- Fish School ..... 11-2
- Fish School Center ..... 7-1
- Fish School Speed ..... 7-9
- Fish Tracking ..... 7-3
- F-shift ..... 3-6
- Function Key ..... 6-1

## G

- GAIN ..... 2-7

## H

- Heading Data ..... 4-4
- Heading Mark ..... 4-5
- History Display ..... 4-3
- HOR ..... 3-6
- Horizontal slice Display ..... 8-2

## I

- INIT SET/TEST Menu ..... 5-11
- Interface Unit ..... 13-5
- Interference Rejector (IR) ..... 3-5
- Interference ..... 11-4

## M

- Main Panel ..... 1-2
- Marks and Data ..... 4-1
- Memory Card ..... 9-1
- Memory Card Initialization ..... 9-1
- Menu Tree ..... A-1

## N

- Nav Data ..... 4-6
- Net Behavior ..... 7-14
- Net Location Mark ..... 7-13
- Net Shooting Mark ..... 9-4
- Net Sonde Data ..... 4-6
- Net Sonde Mark ..... 9-4
- Net Sonde Transmitter ..... 14-2
- Noise ..... 11-4
- Normal Display Mode ..... 4-1
- Normal Display Mode w/text ..... 4-2
- North Mark ..... 4-4
- Noise Limiter (NL) ..... 3-6

## O

- Overvoltage Warning ..... 12-1

## P

- Port/starboard Display ..... 8-1
- Pulselength ..... 3-3

## R

- RANGE and Bearing ..... 12-7
- Range Ring ..... 4-5
- Rejecting Sonar Interference ..... 3-4
- Remote Control Box ..... 1-8

## S

- Saving the Picture ..... 9-2
- Sea Surface Reflection ..... 11-3
- Seabed ..... 2-3, 11-1
- Self Test ..... 13-1
- Ship's Track Mark ..... 4-6
- Sidelobe ..... 11-4
- Sub Panel 1 ..... 1-4
- Sub Panel 2 ..... 1-5
- Suppressing Seabed Tail ..... 3-3
- SYSTEM menu ..... 5-5

## T

- Target Lock ..... 5-6
- Target Lock Mark ..... 4-7
- Target Slice Display ..... 7-15
- TILT Angle ..... 2-3
- TILT Lever ..... 2-3
- Trackball Mark ..... 4-4
- Transducer Warning ..... 12-1
- Tx Cycle ..... 3-5
- True Motion Display ..... 7-12
- TVG ..... 3-1

## U

- User Menu ..... 5-1
- User Menu Tree ..... 10-1

## V

- VER ..... 3-6